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Development of the Personnel-Based System Evaluation Aid (PER-SEVAL) Performance Shaping Functions

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This report describes how the Personnel-Based System Evaluation Aid (PER-SEVAL) performance shaping functions were developed. It describes how PER-SEVAL will use these functions to identify minimum levels of personnel characteristics for a particular contractor's design. Finally, procedures for future validation of the functions are outlined.

The PER-SEVAL performance shaping functions were developed by conducting regression analyses of data obtained from the U.S. Army Research Institute for the Behavioral and Social Sciences' Project A database. They predict task performance as a function of personnel characteristics and training. Separate functions are provided for different types of tasks. Two types of training variables are used in the performance shaping functions—frequency and recency of practice.

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This report describes how the Personnel-Based System Evaluation Aid (PER-SEVAL) performance shaping functions were developed. PER-SEVAL is one of six automated aids being developed under the HARDMAN III development program. The objective of PER-SEVAL is to find values for the personnel characteristics that will meet system performance requirements given fixed values for conditions, training, and design. In essence, PER-SEVAL estimates the personnel quality requirements of a particular contractor's design.

Other automated tools in the HARDMAN III contract will assist U.S. Army personnel in developing system performance requirements; identifying manpower, personnel, and training constraints; determining maintenance manpower requirements; and assessing operator workload. HARDMAN III is one of several automated tools being developed for Army analysts by the U.S. Army Research Institute for the Behavioral and Social Sciences MANPRINT Division.

DEVELOPMENT OF THE PERSONNEL-BASED SYSTEM EVALUATION AID (PER-SEVAL) PERFORMANCE SHAPING FUNCTIONS

EXECUTIVE SUMMARY

Requirement:

To ensure the personnel quality requirements of new weapon systems, quantitative methods for predicting the impact of personnel characteristics on soldier performance must be developed.

Procedure:

Researchers conducted regression analyses on selected data from the U.S. Army Research Institute for the Behavioral and Social Sciences Project A data base. Separate analyses were conducted for different types of tasks. In each analysis, an attempt was made to predict performance as a function of the Armed Forces Vocational Aptitude Battery (ASVAB) composite and the frequency and amount of sustainment training.

Findings:

Performance shaping functions were developed for most of the task types. It was impossible to develop functions for several types of tasks because there were so few instances of these tasks in the Project A data base.

Utilization of Findings:

The performance shaping functions will be incorporated into the Personnel-Based System Evaluation Aid (PER-SEVAL). PER-SEVAL will assist Army analysts in assessing the personnel quality requirements of future Army systems. The functions could also be used in other tools required to predict task performance as a function of aptitude and sustainment training. The authors recommend that the performance shaping functions be validated in future ARI studies.

DEVELOPMENT OF THE PERSONNEL-BASED SYSTEM EVALUATION AID (PER-SEVAL) PERFORMANCE SHAPING FUNCTIONS

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DEVELOPMENT OF THE PERSONNEL-BASED SYSTEM EVALUATION AID (PER-SEVAL) PERFORMANCE SHAPING FUNCTIONS

Introduction

Objective of Paper

This paper has two objectives. First, it describes how the Personnel-Based System Evaluation Aid (PER-SEVAL) performance shaping functions were developed. Second, it describes how these functions will be used to identify minimum levels of personnel characteristics for a particular contractor's design.

The paper builds on two earlier reports: the PER-SEVAL concept paper, which was delivered to ARI in April 1987, and the PER-SEVAL design specifications, which were delivered to ARI in December 1987.

Overview of PER-SEVAL

PER-SEVAL is one of six automated aids being developed under the MANPRINT methods contract. Figure 1 outlines the objective of PER-SEVAL. Performance is a function of personnel characteristics, conditions, training and the system design (and many other things as well, but these are the variables addressed by PER-SEVAL). The objective of PER-SEVAL is to find values for the personnel characteristics that will meet system performance requirements given fixed values for conditions, training, and design. In essence, what PER-SEVAL does is to estimate the personnel quality requirements of a particular contractor's design.

Performance = F(P,C,T,D)

P - Personnel Characteristics

C = Conditions

T - Training

D - Design

Objective: Find Values for "P" that Meet Performance Requirements Given Fixed Values of C, T, D.

Figure 1. Objective of PER-SEVAL.

The personnel quality requirements produced by the PER-SEVAL Aid will be part of the overall evaluation of a contractor's design. Evaluations may be made as early as the proof-of-principle phase of the acquisition process and would probably be continued in subsequent phases. The primary users of the

PER-SEVAL Aid would be the Directorate of Combat Developments personnel who provide input to the Cost and Operational Effectiveness Analysis (COEA) and the Logistic Support Analysis (LSA); and the logistics division of the program manager's staff who develop manpower and personnel information for the LSA.

The PER-SEVAL Aid receives critical inputs from three other MANPRINT methods aids--The System Performance and RAM Criteria Aid, The Personnel Constraints Aid, and The Manpower-Based System Evaluation Aid. The System Performance and RAM Criteria Aid (SPARC) produces estimates of system performance requirements. The Manpower-Based System Evaluation Aid (MAN-SEVAL) identifies the jobs and tasks associated with each contractor's design. The Personnel Constraints Aid (P-CON) describes the projected distribution of each personnel characteristic.

The PER-SEVAL Aid has three basic components. First, the PER-SEVAL Aid has a set of performance shaping functions that predict performance as a function of personnel characteristics and training. Second, the PER-SEVAL Aid has a set of stressor degradation algorithms that degrade performance to reflect the presence of critical environmental stressors. Third, the PER-SEVAL Aid has a set of operator and maintainer models that aggregate the performance estimates of individual tasks and produce estimates of system performance.

Figure 2 provides an overview of the procedures a user would employ in using PER-SEVAL. The user begins an application of the PER-SEVAL Aid by applying the performance shaping functions using the mean level of the personnel characteristics and the estimated amount of training for the new system. These performance estimates are then input into the stressor degradation algorithms where performance is degraded to reflect the presence of the stressors. Next, the revised task performance estimates are input into the operator and maintainer models which aggregate them to produce estimates of system performance. Then, required performance is compared with estimated performance at either the task or system level (the user selects the level). If performance is adequate, the PER-SEVAL Aid stops. Otherwise, the personnel characteristics are incremented or decreased and the entire process is iterated until required performance levels are met.

Overview of Performance Shaping Functions

PER-SEVAL performance shaping functions predict task performance as a function of personnel characteristics and training. Separate functions are provided for different types of tasks. Two types of training variables are used in the

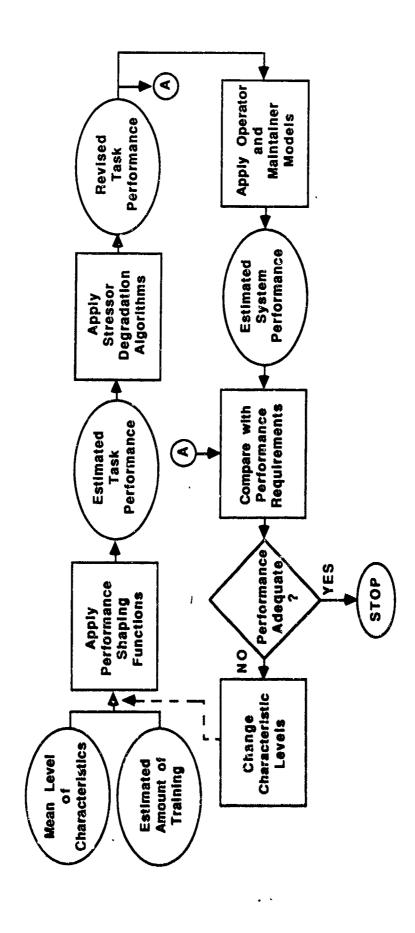


Figure 2. Overview of PER-SEVAL aid logic.

performance shaping functions -- frequency and secency of practice. The primary data source for the development of the performance shaping functions was the Project A data base.

Definition of personnel characteristics.

The performance shaping functions (PSFs) attempt to predict performance for "stable design-related" characteristics. These characteristics are defined as follows:

A design-related personnel characteristic is an enduring human attribute that has a significant impact on operator or maintainer performance and has information available to estimate its current distribution within the Army.

One of the ultimate objectives of ARI MANPRINT tool development efforts is to allow Army users to compare the number of people required at or above a particular personnel characteristic level with the number available at or above this level (the latter is produced by P-CON). This type of comparison is only meaningful for stable or enduring personnel characteristics. For the same reason, a personnel characteristic must either have data available to describe its distribution within each Army MOS or we must be able to identify other existing data that can be reasonably generalized to Army MOSs. If we cannot describe a characteristic's distribution, we have no basis for describing its availability and no basis for setting a constraint in F-COM.

To be a design-related personnel characteristic, a characteristic must be related to operator and maintainer performance--namely, task performance time and/or accuracy. If a characteristic is not related to task time or accuracy, there is little a contractor can do to design a system to accommodate a given characteristic level. Four general types of characteristics meet the criteria described above -- cognitive, perceptual, psychomotor, and physical characteristics.

Of these four types of variables, the first three types (cognitive, perceptual and psychomotor) impact how well a task will be performed while the last type of characteristic (physical characteristics) primarily determine if a task can be performed. Since the focus of PER-SEVAL is on predicting how well a given population can perform a task, the PER-SEVAL PSFs focus on tasks falling into the first three categories.

Page 17 lists the specific characteristics included in the PER-SEVAL PSFs.

Training variables in performance shaping functions.

Originally, we intended to use "amount of initial training" as the training variable in our performance shaping functions. However, two problems with this variable were identified. First, there was a lack of data or data bases which could be used to relate this variable to task performance. Second, and perhaps most importantly, to use this variable we would have had to assume that all soldiers had just graduated from initial training since development of models to predict the impact of intervening variables on learning retention, task practice, and subsequent task performance would be very complex.

Because of these problems, it appeared that we would have to leave training completely out of our models. However, we were able to identify two training-related variables in the Project A data base. This data described how frequently and recently within the last six months a soldier had performed a task prior to the hands-on test. Together these two variables can be viewed as describing the amount and recency of practice given to a particular task. Since practice is one of, if not the key, training variable, we decided to use these variables as measures of the amount of sustainment or on-the-job training. Admittedly, these variables capture only a small part of the total systemspecific training provided to Army soldiers. However, these are the only variables on which data was available.

Through some simple assumptions and algorithms, we were able to develop an approach for converting estimates of frequency of performance on the job into the Project A frequency and recency metrics. This allowed us to use an input variable (frequency of performance on the job) that will be more meaningful to PER-SEVAL users.

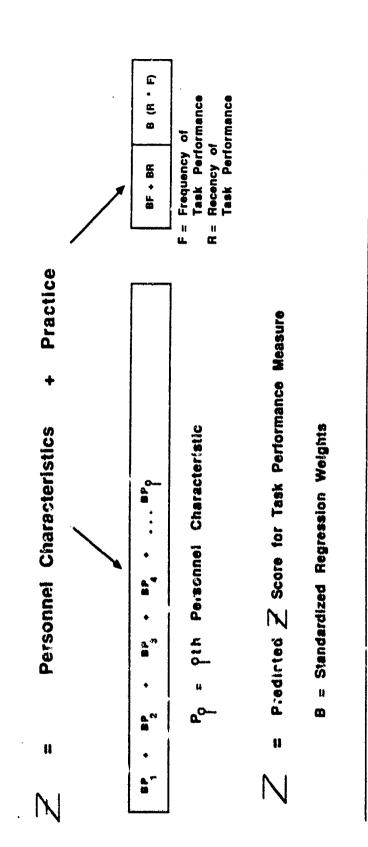
Overview of form of PSFs.

In our concept of the PER-SEVAL, performance shaping functions will be used to predict the performance level that can be expected for a given set of personnel characteristic levels and amount of training. The PER-SEVAL performance shaping functions will actually predict a relative change from a baseline value rather than absolute performance. Also note that the performance shaping functions will describe generic predictor-performance relationships for types of tasks rather than for specific tasks.

Table 1 displays the general form of the PER-SEVAL performance shaping functions. Note that the functions predict a Z score. The PER-SEVAL program will convert the Z score into the raw score using a standard algorithm for converting Z scores to raw scores. However, for the mean score, the program will use the user's estimate of the expected accuracy level for each task

Table 1

General Form of Performance Shaping Functi ns*



associated with the specific contractor's design. (The time estimates produced by MAN-SEVAL are also based on these same assumptions.) This approach allows us to use a generic predictionequation associated with different types of tasks to predict performance on a particular task associated with a specific contractor's design. The mean estimate provided by the user captures the unique design features associated with a particular task. Thus, we assume that the hardware/software design determines the overall or mean level of performance of a task and that personnel characteristics or abilities determine scores of individual soldiers about this mean. This approach requires certain assumptions — some statistical and some conceptual. These assumptions are described in detail on page 79.

Mechanisms for generalizing application of the PSFs to new tasks.

Development of the PER-SEVAL performance shaping functions is different than the typical regression analyses conducted in academic psychology because we are attempting to develop functions that can predict performance for a general class of tasks rather than a particular task. Our ultimate goal is to predict performance for the tasks associated with new weapon systems. Two assumptions or mechanisms allow us to make generalized predictions for new tasks. First, we assume that the generalized relationships we develop for a particular taxon apply to all tasks which fall into that taxon. (On page 87, we outline a set of procedures for validating this assumption). Second, we use the functions to predict Z scores -- that is deviation from a mean value which is tied to specific task's overall task difficulty within a hardware/software design. These two assumptions permit us to develop functions which are scale invariant -- that is, the functions predict performance for any task in that taxon no matter what its scale. This allows us to generalize beyond the specific types of scales (e.g., per cent correct) which were used during PSF development.

History of the performance shaping function concept.

Our concept of performance shaping functions is derived from past work on human reliability analysis. Swain (1967) introduced the term "performance shaping factor" to describe the external and internal factors which modify or influence human performance. Since that time, performance shaping factors have been identified and applied in a wide range of human reliability analyses. A description of performance shaping factors and their use in human reliability analysis is provided in Miller and Swain (1986), and Meister (1985). Performance shaping factors have included "external" variables such as work space layout, environmental conditions, and human engineering design, and internal variables

such as training/experience, skill level, intelligence, perceptual abilities, and physical condition (Miller and Swain, 1987). In a typical human reliability analysis using these factors, task accuracy estimates are first adjusted to account for the impact of the performance shaping factors and these adjusted estimates are combined in a reliability model to produce overall reliability estimates. The impacts of the performance shaping factors on performance are typically expressed as a percentage change from a baseline. Table 2 displays some percentage values that Swain and Guttman (1983) developed to describe the impact of stress on task accuracy for novice and skilled workers.

Data on the impacts of performance shaping factors may be derived from empirical studies or from the application of expert judgment techniques. Miller and Swain (1987) provide a description of recent developments in the application of expert judgment techniques.

Although not labelled as "performance shaping factors" per se, the concept of human performance shaping factors has been used in other areas as well. Human engineering design handbooks often use the performance shaping function approach (percentage impact on a baseline for different types of tasks) to provide guidance for assessing the impact of environmental conditions or other related variables on human performance. For example, Figure 3 lists guidance for assessing the impact of wet bulb temperature on performance for different types of tasks taken from the Handbook of Perception and Human Performance, Boff, Kaufman, & Thomas, 1986.

Constraints on Development of Performance Shaping Functions

Resource and time constraints had a significant impact on the development of the PER-SEVAL performance shaping functions. The general philosophy of the MANPRINT methods contract was to develop automated MANPRINT aids using state-of-the-art technology and existing data. The PER-SEVAL development schedule reflected this philosophy. Consequently, there was neither time nor resources for

- a) the collection of additional task performance data. Thus, we developed the functions using performance data available in existing data bases.
- b) validation of performance shaping function development process. (Page 87 describes a plan for validation).

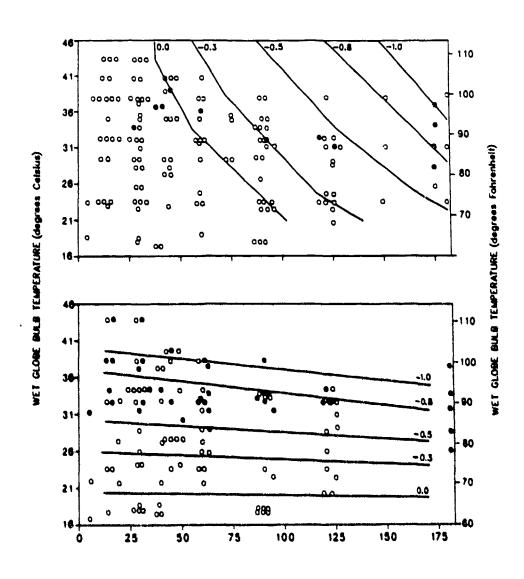
The goal of the PER-SEVAL performance shaping functions is an ambitious one--development of a generic set of functions for predicting performance as a function of personnel characteristics and training using existing data sources that can be applied

Table 2

Model Accounting for Stress and Experience in Performing Routine Tasks*

	% increase in Error Probability		
Stress Level	Skilled	Novice	
Very Low	200	200	
Optimum	100	100	
Moderately High	200	400	
Extremely High	500	100	

^{*}Derived from Swain, A.D., and Guttmann, H.E. (1983, August). Handbook of human reliability and analysis with emphasis on nuclear power plant application (Sandia National Laboratories, NUREG/CR-1278). Washington, DC: U.S. Nuclear Regulatory Commission.



From J.D. Ramsey & S.J. Morrissey. Isodecrement curves for task performance in hot environments. Applied Ergonomics, 9. Copyright 1978 by Butterworth Scientific Ltd., Guildford, Surrey, UK. Reprinted with permission.

Figure 3. Example of the "performance shaping function."

across tasks and MOSs. We believe we have constructed a set of functions that can accomplish this goal and can be incorporated into an automated aid that can be used by Army users to assess personnel quality requirements. However, we recognize that there is much additional work that can and should be done to improve these functions (page 87 describes some of this additional work). Our philosophy has been that it is better to give users a slightly imperfect tool that can help them in the near term rather than to tell them to wait while the "perfect tool" is developed.

Overview of Data Sources for Development of Performance Shaping Functions

The primary data source for the development of the Performance Shaping Functions was ARI's Manpower and Personnel Research Division (MPRD) Project A data base. Project A is more formally known as the project for "Improving the Selection, Classification, and Utilization of Army Enlisted Personnel." To date, Project A is the only data base we have been able to identify that contained the data needed to develop the performance shaping functions. More specifically, the Project A data base has hands-on performance data, personnel characteristics, and training data for nine Army MOS:

- 113 Infantryman
- 13B Cannon Crewman
- 19E Armor Crewman
- 31C Single Channel Radio Operator
- 63B Light Wheel Vehicle Mechanic
- 64C Motor Transport Operator
- 71L Administrative Specialist
- 91A Medical Specialist
- 95B Military Police

The hands-on performance data includes both accuracy and time data. To facilitate aggregation across tasks, the hands-on accuracy measure used on almost all the Project A tasks was "% steps correct." While this measure met the needs of the Project A study, it is, admittedly, not the ideal performance measure for developing PSFs for predicting weapon system task performance for certain types of tasks. (Page 87 describes alternative measures for achieving this objective.) However, since it was the predominant type of accuracy measure in the Project A data base, we had to use it. Still, no matter what measure was used, we had the problem of generalizing to other measures or scales (see page 7).

The Project A data base contained time data on many but not all of the hands-on tasks. Appendix A lists, by MOS, all of the hands-on tasks contained in the Project A data base and their mean accuracy and time measures.

The Project A data also contained personnel characteristic scores for each individual in the data base. Table 3 summarizes the personnel characteristic measures that are included in the Project A data base. Note that the Project A data contained values on seven new predictors developed during the initial stages of Project A. These seven new predictors are actually composites of several subtests (see Table 4). The ASVAB area scores are also composites of several subtests (see Table 4).

The Project A data base also had data on the frequency and recency with which the hands-on tasks were performed. Table 5 lists the scales that were used to assess these measures.

In addition to the Project A data base, the other data source used for performance shaping functions were recent review articles (Genaidy, Asfour, and Tritar, 1988; and Genaidy and Asfour, 1987) on models that predict performance on manual handling tasks. Selected regression models from these articles will be used to predict performance for gross motor tasks.

Because we are using the manual handling regression models "as is" and not developing them "from scratch," there is no discussion of these models in the description of the development of performance shaping functions which follows. These models were described in the "PER-SEVAL Design Specifications" submitted to ARI in December 1987.

Table 3

Key Personnel Characterístics in Project A Data Base

TYPE			VARIABLE	MEAN	STD DEV		MINIMUM MAXIMUM	z
Cognitive	ASVAB	· ASVAB Ares Composites						
	SC	Survelliance Communication	A1AC80SC	106.06	13.50	67	139	5187
	# 00	Combat	A1AC80CO	106.85	12.78		145	5187
	FA	Fleid Artillery	A1AC80FA	104.51	12.53	99	144	5187
	OF =	Operators and Food	A1AC80OF	106.28	11.74	7.1	137	5187
	ST	Skilled Technical	A1AC80ST	103.12	13.66	65	139	5187
	G1 ==	General Technical	A1AC80GT	103.58	12.63	72	130	5187
	# 25	General Maintenance	A1AC80GM	104.43	13.95	9	144	5187
	ה ה	Electronics	A1AC80EL	103.50	13.21	89	141	5187
	۔ در	Clerical	A1AC80CL	102.89	12.82	73	134	5167
	# ====================================	Machanical Maintenance	A1AC80MM	106.84	12.51	89	142	5187
	Numeric	· Numerical Speed and Accuracy*	B3CCNMSA	-98.28	28.40	-318	-38	2067
	Reading	- Reading Grade Level	RGRLVL	9.79	1.56	6.20	12.90	5187
•	· Spatial	•	B3PCSPAT	302.77	43.35	145	401	5193
Perceptual	Complex	· Complex Perceptual Accuracy*	B3CCCPAC	150.82	21.18	30	192	5145
•	Complex	· Complex Perceptual Speed*	Bacccpsp	-48.95	22.89	-175	23	5145
Psychomotor · Psychomotor*	Psychol	motor*	BaccpsyM	-198.09	38.30	-388	-100	5145
	Simple	Simple Reaction Speed*	Baccsasp	.67	15.79	-248	26	5155
•	Simple	· Simple Reaction Accuracy*	B3CCSRAC	100.68	14.38	-25	108	5155

· New Project A Predictor

Table 4
Subtests in New Project A Personnel Characteristics Composites and ASVAB Area Composites

COMPOSITE SCORE	SUBTESTS	ADDITIONAL DESCRIPTION
I. New Project A Personnei Characteristics		
Numerical Speed and Accuracy (B3CCNMSA)	Number Memory Test Number Memory Test Number Memory Test Number Memory Test	Mean for Final Response (Final Decision Time) Mean Hit Rate (Initial Decision Time) Pooled Mean Operation Time (Mean Decision Time) Mean for Initial Input (Percent Correct)
Overall Spatial (B3PCSPAT)	Assembling Objects Test Map Test Maze Test Object Rotation Test Orientation Test Figural Reasoning Test	None None None None None
Complex Perceptual Accuracy (B3CCCPAC)	Perceptual Speed and Accuracy Test Target Identification Test Short Term Memory Test	Mean Hit Rate (Percent Correct) Mean Hit Rate (Percent Correct) Mean Hit Rate (Percent Correct)
Complex Perceptual Speed (B3CCCPSP)	Perceptual Speed and Accuracy Test Target Identification Test Short-Term Memory Test	Mean of Trimmed Decision Time Mean of Trimmed Decision Time Mean of Yrimmed Decision Time
Paychomotor (B3CCPSYM)	Cannon Shoot Test Target Shoot Test Target Shoot Test Target Tracking 1 Target Tracking 2 Pooled Mean Movement Time	Mean Abs. Time Discrep Mean Log (Dist + 1) Mean Time to Fire Mean Log (Dist + 1) Mean Log (Dist + 1) None
Simple Reaction Accuracy (B3CCSRAC)	Choice Reaction Simple Reaction	Mean Percent Correct Mean Percent Correct
Simple Reaction Speed (B3CCSRSP)	Choice Reaction Time Simple Reaction Time	Mean of Trimmed Choice Decision Time Mean of Trimmed Choice Decision Time

Table 4
Subtests in New Project A Personnel Characteristics Composites and ASVAB Area Composites (Cont.)

COMPOSITE SCORE	SUBTESTS	ADDITIONAL DESCRIPTION
II. ASVAB Area Composites		
Cierical (CL)	AR MK VE ¹	Arithmetic Reasoning ASVAB Subtest - AR Math Knowledge ASVAB Subtest - MK Verbal Equivalent ASVAB Subtest - VE ¹
Combat (CO)	AR AS MC CS	Auto & Shop Information ASVAB Subtest - AS Mechanical Comprehension ASVAB Subtest - MC
Electronics Repair (EL)	AR EI MK GS	Electronics Information ASVAB Subtest - El General Science ASVAB Subtest - GS
Field Artillery (FA)	AR MK MC CS	Coding Speed ASVAB Subtest - CS
General Main- tenance (GM)	MK Ei GS AS	
General Technical (GT)	VE AR	
Mechanical Maintenance (MM)	NO EI MC AS	Numerical Operations ASVAB Subtest - NO
Operators and Food (OF)	NO VE MC AS	
Surveillance and Communication (SC)	AR AS MC VE	
Skilled Technical (ST)	VE MK MC GS	

¹ The Verbal Equivalent ASVAB Subtest (VE) is formed by combining scores from the Paragraph Comprehension (PC) and Word Knowledge (WK) ASVAB subtests.

Table 5

Project A Task Frequency and Recency Scales

FREQUENCY

- · Not at All
- •• 1-2 Times (per Six Months)
- •• 3-5 Times (per Six Months)
- •• 6-10 Times (per Six Months)
- .. More than 10 Times (per Six Months)

RECENCY

- .. During Past Month
- · 1-3 Months Ago
- · 4-6 Months Ago
- .. More than Six Months Ago
- · Never

Preparation of Data for Entry into Regression Analyses

Selection of Personnel Characteristics

Seven factors were considered in selecting the personnel characteristics to be included in the PSFs:

- (1) The personnel characteristic had to be included in the Project A data base
- (2) The characteristic had to be a stable design-related characteristic as defined on page 4.
- (3) The characteristic had to have sufficient variability to be used as a predictor. Some of the characteristics we had initially hoped to include (i.e., the PULHES scores) did not have such variability. For example, on some of the PULHES scores, more than 95% of the Project A population had the same score.
- (4) Most of the Project A population had to have scores on the characteristic. For instance, we originally hoped to include MEPSTAT as a characteristic. But only one fifth of the Project A population had scores on this variable. Because this one fifth was spread across the different types of tasks, there was an insufficient sample to use this characteristic.
- (5) A characteristic was excluded if it was incorporated into a higher level measure. (For example, all of the new predictors in the Project A data base were combined into seven composite scores). This approach was taken to: (a) minimize the number of characteristics included in the PSFs, and (b) to improve the reliability of the characteristics (the data suggested that the aggregate measures are more reliable than the lower level measures).
- (6) A characteristic was excluded if it was expected that it would only be related to performance on gross motor-heavy tasks since predictions for these tasks would be handled by the material handling models (see page 11). Three physical characteristics were excluded for this reason-height, weight, and diastolic blood pressure.
- (7) The only ASVAB measures which were included were the ASVAB area composites and the reading grade level derived from the GT composite using conversion algorithms described in Grafton (in press). Other ASVAB measures which were available (e.g., ASVAB Quantitative and ASVAB Verbal) were excluded because of their redundancy with the ASVAB area

composite scores. The area composites are the measures used to control entry into MOSs. Reading grade level was included, despite its near perfect correlation with the GT composite, because of its possible contribution to the prediction of performance in MOSs which did not use the GT composite as a selection tool.

Table 6 lists the final set of personnel characteristics that were included in the regression analyses used to develop the PSFs. The characteristics are divided into three groups—cognitive, perceptual, and psychomotor. Appendix B documents our rationale for excluding particular Project A characteristics.

Development of Task Taxonomy

The MPT² task taxonomy has two major uses. First, it was used to guide the development of the PSFs -- different functions were developed for the different taxons in the taxonomy. Second, it was used to guide the development of the stressor degradation algorithms -- different algorithms were developed for different types of tasks.

In developing the MPT2 task taxonomy, we attempted to develop a classification scheme which would: (a) provide the minimum number of taxons needed to achieve the two objectives described above, and (2) classify tasks and not task elements. The first objective was important because we want to minimize user input requirements and PSF development costs. The latter objective was important because we want the PER-SEVAL models to be applicable at the task level. That is, we want users to be able to assign an individual task to one or more taxons without requiring them to identify specific elements constituting that task. In doing so, we can significantly reduce user input data requirements (users who want to apply the models at the task element level can do so). It should be noted that many behavioral classification schemes, such as Fleishman's (Fleishman and Quaintance's, 1984), are very detailed and are more applicable at the task element level.

The PER-SEVAL task taxonomy is primarily an expansion of Berliner's (1966) task taxonomy. However, an attempt was made to incorporate key features of Wicken's (1981) structure for processing rescurces. These two structures are reasonably congruent with one another. Task types were eliminated which, while possible to imagine on a theoretical basis, seldom occur in the Army e.g., auditory pattern recognition/discrimination). Table 7 displays the PER-SEVAL task taxonomy. Some of the lower level taxons in the hierarchy (see the highlighted taxons in Table 7) are only used in the stressor degradation algorithms and are not used in the PSFs.

Table 6
Personnei Characteristics Used to Develop New PSFs

Type	
Cognitive	ASVAB Area Composites
	SC = Surveillance Communications
	CO = Combat
	FA = Field Artillery
	OF = Operators and Food
	ST = Skilled Technical
	GT = General Technical
	GM = General Maintenance
	EL = Electronics
	CL = Clerical
	MM = Mechanical Maintenance
	Numerical Speed and Accuracy*
	Reading Grade Level
	• Spatial*
Perceptual	Complex Perceptual Accuracy*
	Complex Perceptual Speed*
Psychomotor	Psychomotor*
	Simple Reaction Speed*
	Simple Reaction Accuracy*

^{*} N:w Project A Predictor

Table 7

MPT² Task Taxonomy

Type	Taxon
Perceptual	Visual Recognition/Discrimination
Cognitive	Numerical Analysis
	 Information Processing/Problem Solving
Motor	• Fine Motor - Discrete
	• Fine Motor - Continuous
	Gross Motor - Light
	Gross Motor - Heavy
	- Lifting, Lowering*
	Torquing/Pulling*Carrying*
Communication	• Oral
	- Face to Face - Non-Face to Face
	Reading and Writing



- = this level of taxon only used in stressor degradation models
- These taxons used only in material handling models

Definitions and examples of each of the taxons are provided in Appendix C.

Linkage of Personnel Characteristics to Task Taxonomy Categories

Table 8 displays our estimates of the personnel characteristics that can be expected to predict performance for each of the taxons in the task taxonomy. ASVAB area composite is listed as a potential predictor for each taxon. Four of the new Project A predictors (complex perceptual accuracy, complex perceptual speed, simple reaction speed, and simple reaction accuracy) are also listed as potential predictors for every taxon. However, the two accuracy measures (complex perceptual accuracy, simple reaction accuracy) were used to predict task accuracy and the two speed measures (complex perceptual speed and simple reaction speed) were used to predict task time. The logic underlying these assignments was that these composites were complex and not easily assigned to a particular taxon. remaining two Project A predictors (numerical speed and accuracy and psychomotor) could be readily tied to specific taxons. Numerical speed and accuracy is expected to be a predictor of the numerical taxon. Psychomotor is expected to be a predictor of the four psychomotor taxons. Reading grade level is expected to be a predictor of the communication - reading and writing taxon.

Assignment of Project A Tasks to Taxons

Using the definitions listed in Appendix C, DRC staff assigned each of the Project A hands-on tasks to one or more of the taxons. Each task could be assigned to a maximum of three taxons. We also estimated the expected percentage of task elements involving each taxon. This process paralleled the (expected) approach that users will take in assigning tasks to taxons in PER-SEVAL (see page 77 for a description of this process). The assignments and estimated percentages for each task are listed in Appendix A.

Table 9 displays the distribution of the hands-on tasks across taxons within each MOS based on the primary taxon assignment. Note that one of the taxons (gross motor-heavy) was not represented in the Project A data base. This does not pose a problem since we planned on using existing manual handling models for this type of task (see page 12). For several of the other taxons (e.g., visual recongnition/ discrimination, gross motor-light), there was a small number of tasks in the Project A data base. This posed a problem since we needed multiple tasks within the same taxon in an MOS to build a taxon performance measure. (Without such a measure, we cannot develop a PSF for that taxon.) To overcome this problem, we began to examine the knowledge test items in the Project A data base as a possible additional source of task items. We did this because we believed that for certain

Table 8

Personnel Characteristics Expected to be Predictors of Taxon Performance Measures

*This characteristic is unique to the Project A data T = Predictor of TIME only A = Predictor of ACCURACY only

Table 9

Distribution of Hands-On Tasks Across Taxons*

		118	138	19E	310	8£9	64C	71L	91A	95B	TOTAL
1.1	Perceptual - Visual Recognition/Discrimination	1 (.07)	0	٥	0	0	1 (.06)	0	0	0	2
2.1	Cognitive - Numerical	1 (0.7)	13 (.18) 1 (.07)	1 (.07)	1 (.07)	1 (.07)	2 (.13)	1 (.07)	1 (.06)	5 (.29)	26
2.2	Cognitive - Reason/PS/Dia.	0	0	•	4 (.27)	3 (.20)	0	0	0	1 (.06)	80
3.1.1	Fine Motor - Discrete	8 (.57)	8 (.57) 14 (.82) 11	11	9 (.60)	10 (.67) 12 (.75) 10 (.71) 15 (.88) 10 (.59)	12 (.75)	10 (.71)	15 (.88)	10 (.59)	66
3.1.2	Fine Motor - Continuous	2 (.14)	0	0	0	0	1 (.06)	0	٥	0	6
3.2.1	Gross Motor - Heavy	•	•		•	•	•	•	ı		
3.2.2	Gross Motor Light	2 (.14)	0	1 (.07)	0	0	•	0	0	0	3
4.1	Communication - Reading and Writing	0	0	0	0	0	0	3 (.21)	1 (.06)	0	•
4.2	Communication - Oral	0	0	2 (.13)	1 (.07)	1 (.07)	0	0	0	1 (.06)	3
	Total	14	17	15	15	15	16	14	17	17	140

" Numbers in perentheses refer to percentage of tasks failing into that taxon for each MOS.

< × 0 z

taxons (e.g., communication-reading/writing) there was a great deal of similarity in the way that Project A hands-on and knowledge items were measured--that is, actual performance of the task tapped by the hands-on measures played a small role in overall task performance. Thus, we decided to include knowledge items for the four taxons without a significant psychomotor component, (i.e., visual recognition/discrimination, cognitive-numeric, cognitive-reasoning/problem solving/decision making, and communication reading/writing). Pages 26 to 36 describe the knowledge items included in each taxon.

Selection of Tasks For Taxon Measures

In order to predict performance, we selected a set of tasks to represent each taxon. Since we intended to construct taxon performance scores by aggregating across tasks falling into that taxon for a particular individual, all of the tasks selected for a particular taxon had to come from the same MOS. Two criteria were used to determine which MOS would represent a particular taxon. First, the MOS had to have a relatively large number of tasks falling into a particular taxon. It is important to stress the word "relatively" because for some taxons the maximum number of tasks within any MOS was only 2 or three. Second, where there were several MOSs to select from, we selected the MOS which (a) had available training frequency and recency and time data and (b) had a relatively large number of hands-on task items. The emphasis on the hands-on measures reflects our overall preference for the hands-on measures.

In selecting tasks to represent a taxon, we also examined the contribution of individual tasks to overall scale consistency (coefficient alpha). We used this examination as a statistical check on our taxon assignments. Assignments for tasks which were not consistent with the overall scale were reexamined. This was accomplished by reviewing the Project A descriptions. Based on this review, taxon assignments were changed for a few of the tasks. However, if the taxon assignment was deemed appropriate, it was left in the taxon measure despite its lack of statistical consistency with the overall measure. We used this procedure because we wanted to take a predominantly rational rather than a purely empirical approach to the construction of taxon scale measures.

Table 10 lists the MOSs selected to represent each taxon and the types of tasks included in each taxon measure. A more detailed description of the tasks selected for each taxon follows.

Visual recognition/discrimination.

Table 11 summarizes the tasks used to construct the performance measures for this taxon. Only two MOSs (11B and 64C)

Summary of MOSs and Tasks Used to Construct Taxon Measures

Table 10

	(Number Tasks Us	Number of Hands-On Tasks Used in Taxon	Number Items U	Number of Knowledge Items Used in Taxon	Total Num Used	Total Number of Tasks Used in Taxon
	MOS to be	Me	Measure	Ž	Measure	Me	Measure
Taxon	Used	TIME	ACCURACY	TIME	ACCURACY	TIME	ACCURACY
Visual Recognition/ Discrimination	118	•	-	•	-	•	8
Numerical Analysis	958	က	S.	1	•	5	5
Information Proces- sing/Problem Solving	31C	4	ഗ	•	ဧ	4	သ
Fine Motor - Discrete	95B	œ	10	•	1	10	10
Fine Motor - Continuous		Insuffic	insufficient data to develop PSFs	elop PSFs			
Gross Motor - Heavy		Material	Material handling models used	s used			
Gross Motor - Light	118	•	2	•	•	•	8
Communication - Reading and Writing	71L	8	ಣ	4	7	2	10
Communication - Oral	19E	2	2	•	ŧ	2	2

Table 11

Description of Tasks Used in Constructing Taxon Measure: Visual Recognition/Discrimination

TAXON 1.1 MOS 11B

PROJECT A			ACC	CCURACY		F	TIME 1		FREC	FREQUENCY		REC	RECENCY		·	OTHER		
TASK CODE	TASK TITLE	TYPE MEAN		8.D.	Z	S.D. N MEAN S.D. N MEAN S.D. N MEAN S.D. N NAME MEAN S.D.	S.D.	×	MEAN	8.D.	22	MEAN	8.D.	R	NAME	MEAN		z
FHQS	Conduct Day and Night Survellance Without Ald of Electrosic Devices [Total Score (75) Measure]	НоТ	74.47	30.44 658	659	•	•	ı	2.87	1.45	•••	2.87 1.45 691 2.60 1.37 688	1.37	::	•	•	•	
XKQ3	M Armored Vehicles [PC tack]	Kaow 67.36		19.60 691	•						•				,			

MOTE: In the column labeled TYPE, ThoT' represents Heads-On-Tests in the Project A Concernent Validity Database, and "Know" represents knowledge or paper and pencil tasks.

had tasks in this taxon and each of these only had one task. The 11B task (Conduct Day and Night Surveillance Without the Aid of Electronic Devices) was especially interesting because rather than using "% steps correct," a measure of the % correct visual identifications was used. (The actual measure was targets correctly located in one minute plus total targets correctly located minus false detections). Consequently, we decided to use 11B as the source for developing this taxon. To supplement the one hands-on task for 11B, we decided to use one knowledge item for the task "Identify Armored Vehicles." In testing this item, soldiers were shown photographs of actual armored vehicles and asked to identify the vehicle from a set of choices.

Cognitive - numerical.

Table 12 summarizes the tasks used to construct the performance measures for this taxon. Only MOS 95B, had more than two tasks falling into this taxon --hence, 95B data was used to develop the cognitive-numerical taxon.

Table 12

Description of Tasks Used in Constructing Taxon Measure: Cognitive - Numerical Analysis

TAXON 2.1 MOS 958

PROJECT A			25	ACCURACY		#	TIME 1		FRE	FREGUENCY	,	RE	RECENCY			OTHER		
TASK CODE	TASK TITLE	TYPE	MEAN	\$.D.	2	HEAN	8 .0.	*	WEAN	S.D.	Z	MEAN S.D.	8.D.	Z	HAME	MEAN	8.D.	2
BKQ\$	Estimate Punge	#e7	33.83	30.08	670	•	,		2.26	1.31	783	684 3.04 1.48 677	1.48	677			•	
XHC1	Determine a Magnetic Azimuth Uting a Compass	HeT	81.18	25.83	***	68.63 26.58 634	34.58	634	3.01	1.33	487	2.27	1.10	•				
XHC3	Determine Orld Coardination of a Point on a falling the falling the falling the falling the falling the falling the falling to the falling	MoT	84,98	16.41	67.4	88.82 162.87 689	162.67		3.25	1.20	\$00	1.00		2	680 Time 2 38.00 28.03 627	39.00	28.03	627
XHC.	Call For/Adjust Indirect Fire	MOT	19.61	18.73	***	57.60 44.71 436	44.71	436	1.62 0.86		***	888 3.78 1.20	1.20	673	Time 2	88.44 \$8.05 390	80.8	380
XHC7	Navigate from One Point on the Ground to Anather Point	HeT	84.73	24.58	755		•	•	2.62	1.32		2.69	1.31	675	•			.

NOTE: In the solumn labeled TYPE, "NoT" represents Handa-On-Tasks in the Project & Concurrent Validity Database, and "Know" represents knowledge or paper and penali tasks.

Cognitive - reasoning/problem solving/decision making.

Table 13 summarizes the tasks used to construct the performance measures for this taxon. MOS 31C had five hands-on tasks falling into this taxon and three tasks with clearly relevant knowledge measures, which were also used in the taxon measure.

Table 13

Description of Tasks Used in Constructing Taxon Measure: Cognitive - Information Processing/ Problem Solving

TAXON 2.2 MOS 31C

4 2000			ACC	CCURACY		F	TIME 1		FRE	FREQUENCY		RE	RECENCY			OTHER		
TASK CODE	TASK TITLE	TYPE	MEAR	3.D.	z	MEAN	S.D.	z	MEAN	S.D.	z	MEAN	S.D.	z	KAME	MEAN	S.D.	z
СИНЭ	Perform Operator's Troubleshooting Procedures on Generator Set [PU-620]	HOT	\$0.2≠	25.47	343	,	,		3.18	1.55	346	2.21	1.43	347		•		
GHI1	Op. Teletypenviter AN/GRC-142	doT	76.86	16.27	336	315.27 211.94	211.84	313	3.06	1.58	356	2.41	1.48	3.50				
GHJ1	EstablEnterilenve Radio Not [Includes Time Measure (T1]]	НоТ	62.23	26.66	339	313.94 194.40	184.40	331	3.71	÷	354	1.96	1.21	356			•	
анлз	Use the KTC 1400 D Numerical Cipher/Authentication System	Hoř	58.88	34.58	340	392.89	186.40	324	3.17	1.40	356	2.35	1.33	356			,	
CH14	Prepare a Message in 16-line Format	HoT	37.96	19.20	347	337.37 147.92	147.92	318	3.76	1.47	353	2.04	1.21	357				
GK12	Troubleshoot GRC-142 [PC Tesk]	Know	52.83	21.53	351	,	•	٠	٠		•							
GK16	Troubleshoot GRC-108 [PC Teek]	Ksow	62.02	27.08	336	•		•	•	•	٠							•
GKJ2	Operate in Radio Note (PC Test)	Know	56.27	22.41	348	•	,	,		٠				•				

NOTE: In the column labeled TYPE, "Hot" represents Hands-On-Tasks in the Project A Concurrent Validity Database, and "Know" represents knowledge or paper and pencil tasks.

Fine motor - discrete.

Table 14 summarizes the tasks used to construct the performance measures for this taxon. Since most of the Project A hands-on measures fell into this taxon (this is not surprising since the % steps correct metric is most appropriate for this type of task), there were many MOSs to select from. We selected 95B because it had training frequency and recency data for each fine motor - discrete task and because it had time data available for the vast majority (eight out of ten) of these tasks.

Table 14

Description of Tasks Used in Constructing Taxon Measure: Fine Motor - Discrete

TAXON 3.1.1 MOS 95B

PROJECT A			ACC	ACCURACY		1	THAE 1		FRE	FREQUENCY		RE	RECENCY			OTHER	œ	
TASK CODE	TASK TITLE	TYPE	MEAN	S.D.	R	MEAN	s.D.	2	MEAN	S.D.	Z	MEAN	S.D.	z	NAME	MEAN	S.D.	z
BHE1	Prepare/Operate FM Radio Set	HOT	75.63	17.44	874	331.6	162.96	574	3.28	1.5	989	2.1	1.22	680				ŀ
3 HH 1	Perform/Operator/Craw Praventive Maintenance Checks and Services	HoT	76.26	15.19	17.1	•	,		4.4	1.12	888	1.42	8	188				·
BHLS	Use Nand and Arm Signals to Direct Traffic	НоТ	81.82	22.72	676	,			3.59	1.47	6.87	1,98	÷.18	683				· _
XHA2	Perform Cardiopulmonary Resuscitation (CPR) on an Adult Using the One-Man Method	HoT	69.72	26.41	662	33.49	24.15	542	2.09	1.2	8 8 8 8	3.21	1.3\$	08.8	Time 2	182.84	282.27	540
XHA4	Put On-Field or Preseure Dressing	HoT	74.12	20.61	283	6.8.8	34.11	533	2.42	1.31	687	2.7	1.32	189	Time 2	48.47	35.03	504
XHB1	Operate and Maintain a .43 Caliber Pistol	HoT	87.25	10.66	623	11.89	2.0	621	4.36	1.13	:	1.45	0.86	684	Time 2	18.73	18.98	613
									-						Time 3	42.32	23.30	619
<u></u> .															Time 4	82.46	54.31	613
														-	Time 5	13.04	13.31	602
XHB2	Operate and Maintain a .38 Caliber Revolver	HoT	90.34	11.18	05	114.18	7:55	;	٠	•	•		•		Time 2	12.64	15.66	8
хивз	Load, Reduce a Stoppage, and Clear on Mitch? Ritio	НоТ	64.27	14.19	289	12.21	9.16	089	3.36	1.4	:	2.11	1.13	682	•			<u> </u>
XHBS	Load, Reduce a Stoppage and Clear MED Machinegun	NoT	63.43	20.01	67.6	\$7.07	23.53	5	2.89	1.48	687	2.6	1.3	188	Time 2	25.59	16.30	627
															Time 3	29.88	26.47	628
хнох	Put On, Wear, Remove M17 Protective Mask with Hood	НоТ	85.6	17.28	L 99	8.72	2.56	651	3.62	1.29	988	1.83	0.91	662	Time 2	9.94	6.63	633
																		İ

NOTE: in the column isbeled TYPE, "Hol' represents Hands-On-Tasks in the Project A Concurrent Validity Database, and "Know" represents knowledge or paper and pencil tasks.

Fine motor - continuous.

There was only one task falling into this taxon in the entire Project A data base--Operate Tractor and Semitrailer from MOS 64C. Additionally, this task was tested using a metric (i.e., % steps correct) that we felt didn't adequately measure the "fine motor-continuous" aspects of the task. Consequently, we decided not to attempt to build a PSF for this taxon. Page 87 describes our approach for dealing with the lack of PSF for this taxon.

Gross motor - light.

Table 15 summarizes the tasks used to construct the performance measures for this taxon. We decided to use 11B since it was the only MOS with more than one task falling into this taxon.

Table 15

Description of Tasks Used in Constructing Taxon Measure: Gross Motor - Light

TAXON 3.2.2 MOS 11B

PROJECT A			VC	ACCURACY		F	TIME 1		FREC	FREQUENCY		RE	RECENCY	Г		ОТНЕВ	_	
TASK CODE	TASK TITLE	TYPE	TYPE MEAN S.D. N MEAN S.D. N MEAN S.D. N MEAN S.D. N NAME MEAN S.D.	S.D.	×	MEAN	S.D.	æ	MEAN	8.D.	z	MEAN	S.D.	z	NAME	MEAN	S.D.	2
FHBS	Engage Enemy Target with Hand Granades	НоТ	11.41	11 22.67 683	683	•	•	,	2.90	1.33	:	2.90 1.33 694 2.64 1.25 689	1.25	# # # # # # # # # # # # # # # # # # #				
FHJI	Tech. of Urban Terr. Movement	НоТ	71.98	98 22.01 683	683	•			2.51	1.32	1.83	2.51 1.32 691 3.00 1.29 686	1.29	888		·		

NOTE: In the column Inheled TYPE, "Hot" represents Hands-On-Tasks in the Project A Concurrent Validity Database, and "Know" represents knowledge or paper and pencil tasks.

Gross motor - heavy.

No Project A tasks fell into this taxon. Performance for tasks falling into this taxon will be predicted using the materials handling models (see page 11).

Communication - oral.

Table 16 summarizes the tasks used to construct the performance measures for this taxon. Both 19E and 95B had two tasks falling into this taxon. We decided to use 19E since this MOS contained weapons system operators.

Table 16

Description of Tasks Used in Constructing Taxon Measure: Communication - Oral

TAXON 4.2 MOS 19E

			AC	ACCURACY		F	TIME 1		FRE	FREQUENCY		Ä	RECENCY			OTHER	_	
TASK COGE	TASK TITLE	TYPE	TYPE MEAN	S.D.	Z	S.D. N MEAN S.D.	S.D.	z	MEAN S.D.	S.D.	Z	MEAN	S.D.	z	MEAN S.D. N NAME MEAN S.D.	MEAN	S.D.	2
EHES	Use an Automated CEOI	HoT	48.88	38.60	487	38.60 487 200.13 98.00 368 2.48 1.41 491 2.71 1.55 489	98.00	368	2.48	1.41	187	2.71	1.55	489				
хнет	Sond a Radio Message	НоТ	HoT 65.89	34.68 486	•	•			3.80	1.32	483	3.80 1.32 483 1.68 0.95 490	0.95	490				

NOTE: In the column labeled TVPE, "Hot" represents Hands-On-Tasks in the Project A Concurrent Validity Database, and "Know" represents knowledge or paper and pencit tasks.

Communication - reading/writing.

Table 17 summarizes the tasks used to construct the performance measures for this taxon. 71L had the most hands-on tasks (3) falling into this taxon. In addition, 71L had a number of clearly relevant knowledge items which fell into this taxon (see Table 17). Most of these items involved reading and evaluating typed material.

Table 17

Description of Tasks Used in Constructing Taxon Measure: Communication - Reading and Writing

TAXON 4.1 MOS 71L

NOTE: In the column labeled TYPE, "Hot" represents Hands-On-Tasks in the Project A Concurrent Validity Database, and "Know" represents knowledge or paper and pencil tasks.

Construction of Criterion Measures

The objective of the PSF development effort was to develop functions to predict performance for different types of tasks as a function of personnel characteristics and training. We are interested in predicting performance for a task type rather than a specific individual task. Thus, our dependent measure was mean task performance for a particular task type rather than performance on a specific task.

To construct mean task performance measures for each taxon, we first developed standardized scores for each task by calculating the mean and standard deviation for the MOS on that task. We then took the mean of these standardized scores across the tasks falling into the taxon for a particular individual. We used standardized scores because tasks falling into the same taxon sometimes used different scales. For the most part, "% steps correct" was used as the criterion accuracy measure for Project A tasks. However, for a number of tasks, other scales (e.g., total targets correctly located) were used.

The same procedure was used to construct mean values for both time and accuracy: standardized scores were developed for each task and the standardized scores were averaged to create an overall taxon measure. Time values were not available for all Project A tasks; so in some cases the number of tasks used to construct the mean time values was different than the number of tasks used to calculate the mean accuracy values (see Table 10).

Construction of Predictor Measures

Table 18 summarizes the predictor variables used to develop the PSFs and the calculations, if any, that were needed to create these variables.

Construction of reading grade level score.

A reading grade level (RGL) score was calculated using a transformation table developed by Grafton (in press). The table lists values for converting scores on the GT ASVAB area composite to RGL.

Calculation of mean training frequency and recency scores.

Mean training frequency and recency scores were calculated for each taxon by averaging across the tasks which fell into that taxon. Frequency and recency scores were not available for all tasks. (See Table 19)

Table 18

Calculations Required to Construct Predictor Variables

PREDICTOR	CALCULATIONS REQUIRED
ASVAB Area Composites	None
Numerical Speed and Accuracy	None
Reading Grade Level	Derived from GT in Accordance with Grafton (in press)
Spatial	None
Complex Perceptual Accuracy	None
Complex Perceptual Speed	Non●
Psychomotor	None
Simple Reaction Speed	None
Simple Reaction Accuracy	None
Frequency	Calculated by Averaging Across Tasks in Texon
Recency	Calculated by Averaging Across Tasks in Taxon
Frequency-Recency Interaction Term	Calculated by Multiplying Frequency and Recency Scores
Accuracy*	

^{*} Used as a predictor for time only

Table 19
Mean Frequency and Recency Scores per Taxon

	0 0 0 N	Frequency	ency	Recency	ncy
Тахоп	te Used	MEAN	S.D.	MEAN	S.D.
Visual Recognition/ Discrimination	118	2.87	1.45	2.60	1.37
Numerical Analysis	958	2.55	0.94	2.75	0.85
Information Processing/ Problem Solving	310	3.51	1.15	2.12	0.93
Fine Motor - Discrete	958	3.34	0.86	2.15	0.69
Fine Motor - Continuous	PSF not ye	PSF not yet determined			
Gross Motor - Heavy	PSF not yet	it determined			
Gross Motor - Light	118	2.70	1.12	2.82	1.02
Communication - Reading and Writing	71.2	2.93	0.93	2.60	0.82
Communication - Orai	361	N/A	N/A	4 / 2	A/N

Construction of frequency-recency interaction term.

We hypothesized that there would be an interaction between training frequency and recency in terms of their impact on performance. For example, one might expect the impact of recency on performance to vary depending on how frequently the task was performed. To include this interaction in the PSFs, we constructed an interaction term by multiplying frequency and recency.

Results of Regression Analyses

Two sets of regression analyses were conducted to develop the PSFs for each taxon. In the first set of regression analyses, performance was predicted as a function of personnel characteristics and training without correcting for restriction of range in ASVAB area composites. In the second set of regression analyses, corrections for these factors were applied. The actual PSFs were constructed from the second set of analyses—that is, the analyses with the correction factors. Results from the first set of analyses are presented to show the impact of the correction factors.

Each set of analyses was conducted in the following manner:

Predictors.

A different set of predictors was used for each taxon (see Table 20). The predictors employed were based on the characteristic-taxon relationships described on page 21. Wherever data was available, frequency and recency and their interaction are used as predictors for each taxon. Actually, 10 separate regression analyses were conducted for each criterion corresponding to the 10 ASVAB area composites. This approach was taken so that PSFs would be available for any MOS regardless of which ASVAB area composite is used as a selection criteria for that MOS.

Criteria.

Separate sets of regression analyses were conducted to predict the accuracy and time measures for each taxon. Thus, 20 regression analyses were conducted for each taxon (10 ASVAB composites times 2 types of performance criteria.)

To predict accuracy, the predictors were entered in three "blocks." In the first block, the relevant ASVAB composite was entered. In the second block, of the training-related variables (frequency, recency, and frequency-recency interaction term) were entered into the equation. In the third block, a stepwise technique was used to determine which of the remaining predictors would enter the equation.

To predict time, the predictors were entered in four blocks. In the first block, the ASVAB composite was entered. In the second block, the training variables were entered. In the third block, the accuracy criterion was entered. In the fourth block, a stepwise technique was again used to determine which of the remaining predictors would enter the equation. Accuracy was used as a predictor of time because of the expected relationship

Table 20 **Expected Predictors for Each Taxon**

	Visual Recognition/	=	Numerical Analysis		-	#ing/Problem Solving	Fine Motor - Discrete		Fine Motor -	Continuous	Gross Motor - Heavy	·	Gross Motor - Light	T	Communication -		Communication - Oral	
	Accuracy	Time	Accuracy	Time	Accuracy	Time	Accuracy	Time	Accuracy	Time	Accuracy	Time	Accuracy	Time	Accuracy	Time	Accuracy	Time
ASVAB Composite	X	N/A1	×	х	×	X	X	X					X	X	X	X	Х	X
Reading Grade Level															x	X		
Complex Perceptual Speed		N/A		X		X		X						X		X		X
Complex Perceptual Accuracy	X		×		X		X						X		Х		X	
Overali Spatial	×	N/A	×	X	X	X	X	X	,	2			×	x	X	X	×	X
Numerical Speed & Accuracy	1		×	×	-													
Psychomotor	1						×	X			Ing		X	X		Т	×	
Simple Reaction Speed		N/A		X		X		X	•			2		X		X		X
Simple Reaction Accuracy	×		×		X		X		1	É	E H	pesn :	×		×		X	
Training Frequency	×	N/A	X	X	X	X	X	X			Heterials Handling	Models	X	X	X	X	N/A ²	N/A ²
Training Recency	×	N/A	x	X	X	X	X	X			Ī	20	X	x	X	x	N/A	H/A
Training Frequency X Recency Interaction	×	H/A	×	×	X	x	X	X					×	×	×	X	N/A	N/A
Acquiracy		N/A		X		X		X						X		X		N/A

Time measures for Visual Recognition/Discrimination and Communication - Oral were not available

2 Training measures for Communication - Oral were not available

between time and accuracy. In PER-SEVAL, we intended to first predict accuracy and then predict time given the predicted accuracy value.

Results From Regression Analyses Without Correction Factors

Table 21 summarizes the results from the regression analyses without the correction factors. In doing the regression analyses without the correction factors, predictors were forced into the equation to mirror the results obtained from the analyses with the correction factors (see below).

Results From Regression Analyses With Correction Factors

Regression analyses were conducted with correction factors for restriction of range due to the use of ASVAB scores as a selection mechanism for entry into the Army and individual MOSs.

Correction for restriction of range.

Entrance into the Army is typically restricted to individuals who score above a minimum value on the Armed Forces Qualification Test (AFQT). The AFQT is a composite of four ASVAB subtests — Arithmetic Reasoning, Word Knowledge, Paragraph Comprehension, and Numerical Operations. Once an individual is accepted into the Army, he or she is assigned to an MOS. However, entrance into the MOS is typically restricted to individuals who score above a minimum value on a particular ASVAB area composite. The ASVAB area composites are also composites of individual ASVAB subtests (Table 4 lists the subtests in each composite). Thus, restriction of range occurs at two levels—entrance into the Army and entrance into the MOS.

The procedure used to correct R for range restriction is one proposed by Lawley (1943) and described in Lord and Novick (1968). In applying the procedure, the variance-covariance matrix of the ASVAB composites for the 1980 youth population was computed using the variance-covariance matrix of the ASVAB subtests (Mitchell and Hanser, 1980). Table 22 lists these intercorrelations. The next step in the correction procedures was to adjust for the MOS selection criteria (i.e., the ASVAB composites). The variances and covariances for the ASVAB composites for each Project A MOS used in the analyses are listed in Appendix D.

Mathematical description of correction procedures.

In describing the equations for correcting for restriction of range or curtailment, we use the following notation:

Summary of Results (Multiple Correlation) for Regression Analyses Without Corrections Table 21

3	Visual Recognition/ . Discrimination	gaftlor/ atlon	Numerical Analysis	nalysis	Information Processing/ Problem Solving	Processing/ Solving	Fine Motor - Discrete	Discrete	Gross Motor - Light	- Ligh	Communication -	ation -	Communication	ation -
COMPOSITE	ACCURACY	TIME	ACCURACY	THE	ACCURACY	TIME	ACCURACY	TIME	ACCURACY	TIME	ACCURACY	TIME	ACCURACY	TIME
Cierical/ Administrative (CL)	.31*	M/A	•66	*	.48•	.23•	.38.	.48.	.17.	N/A	.61*	.174	.16*	
Combat (CO)	.30.	HVA	-40-	.32-	.43	.23	.38.	-84	.17.	N/A	.09	.17.	.23*	18.
Electronics Repair (EL)	.32*	H/A	-00-	:10	.45•	.23*	.38.	.67	.17•	N/A	.09	.21	.20*	
Field Ardil- lery (FA)	.30-	WA	.40•	.32*	.45-	.23*	**6.	.49.	.16.	N/A	.09	.17.	.18*	191
General Main- tenance (GM),	.33*	N/A	.39*	.31	.45*	.24	.40•			N/A	.09	.18+	.43.	*71.
General' Tech- nical (GT)	.30*	WA	.36-	·15.	.45*	.23*	.38.	.49.	.17•	N/A	-09°	.17.	.22.	=
Machanical Maintenance (MM)	.18.	N/A	.38-	.31-	.43*	.23•	.40•	.49.	.17.	A/N	.09.	•71.	.20*	.15+
Operators/ Food (OF)	.33*	MVA	.38•	.32-	.43*	.23*	.39•	.49.	.18*	A/A	-09	+71.	.18*	.77.
Survellance/ Communica- tions (3C)	.18.	HUA	.39•		.44-	.24•	.38	.40	.er.	N/A	.09	.17	.17.	.71.
Skilled Technical (ST)	.32*	H/A	•07	.31*	.>*	.24	.38.	.84.	.1.	N/A	.09.	.17+	.23*	

[.] p c .01

Table 22

Mean, Standard Deviations and Intercorrelations for Population Taking ASVAB: 1980 Reference Population Subtest Scores^a

ASVAB Subtest (N = 9173)

	Arithmetic Reasoning AR	Word Knowledge WK	Paragraph Comprehension PC	Numerical Operations NO		Coding Speed CS	Auto & Shop Information A S	Mathematics Knowledge MK		Electronics information El
AR	10,25									
WK.	.71	50.81 10.05					ł	1		
PC		.80	51.47 9.66							
NO		.60	.60	48.56 10.65					·	
GS	.,,	.80	.69	.52	49.63 9.66					
CS	.51	.55	.56	.70	.45	51.94 10.10				
A S	.53	.52	.42	.29	.64	.22	46.28 9.82			
MK		.67	.64	.62	.69	.52	.41	81.84 10.77		
MC	.68	.59	.52	.40	.70	.33	.74	.60	47,55 9,55	
EI	.66	.68	.57	.41	.76	.34	.75	.58	.74	47.98 9.86

AR = Arithmetic Reasoning

WK = Word Knowledge

PC = Paragraph Comprehension

NO = Numerical Operations

GS = General Science

CS = Coding Speed

AS = Auto and Shop Information

MK = Mathematics Knowledge

MC = Mechanical Comprehension

El = Electronics information

REFERENCE:

Office of the Assistant Secretary of Defense (OASD) [Manpower, Reserve Affairs, and Logistics]. (1982). Profile of American Youth: 1980 Nationwide Administration of the Armed Services Vocational Aptitude Rettery.

Restricted to persons in the sample born between January 1, 1957 and December 31, 1962 (18 through 23 years at time of testing, July-October 1980).

b Means and Standard Deviations along the diagonal. Means are slightly above the diagonal, and standard deviations are slightly below.

- x(X) Variables on which explicit selection has taken place (corresponding variables in the uncurtailed population)
- y(Y) Variables on which incidental selection has taken place (corresponding variables in the uncurtailed population)
- Sx(SX) Variance covariance matrix of the variables on which explicit selection has taken place
- Sy(SY) Variance covariance matrix of the variables on which incidental selection has taken place

We make the following assumptions (Lawley, 1943; Lord and Novick, 1968):

(i)
$$E(Y | X) = E(y | x)$$

(ii)
$$SY.X = Sy.x$$

The first assumption is that the regression equations and, hence, the regression coefficients, are equal in the curtailed and the uncurtailed populations. Since the regression coefficients are given by the expression B = SX-1 SXY = Sx-1 Sxy, it follows that;

$$SXY = SX Sx-1 Sxy$$

The residual, a partial variance-covariance matrix Sy.x is given by the expression:

$$Sy.x = SY - SYX SX-1 SXY$$

Similarly,

$$Sy.x = Sy - Syx Sx-1 Sxy$$

Thus,

$$SY - S'XY SX-1 SXY = Sy - S'xy Sx-1 Sxy$$

and, hence,

$$SY = Sy + S'XY SX-1 SXY - S'xy Sx-1 Sxy$$

or,

$$Sy = Sy + (S'XY - S'xy) Sx-1 Sxy$$

when selection takes place, SX, Sx, Sxy, and Sy are known. Correcting for curtailment requires obtaining SY, and SXY so that the variance-covariance matrix of Y and X in the uncurtailed population can be obtained. Once this matrix is determined, the equation for predicting Y from X in the uncurtailed population can be determined.

In the present context, there are two possible definitions of the uncurtailed population: (a) the 1980 reference population and (b) the population of those selected to enter the Army. The equations given above can be used to correct for restriction of range for these two populations.

Since the 1980 reference population data only includes information on the relationships among subtests (i.e., standard deviations and means), it was necessary to estimate the relationships among the ASVAB composites for this same population. In making these estimates, we assumed that the composites were linear composites of the subtests. In actuality, the composite scores are derived from the subtests using equipercentile-equating techniques. These techniques involve using conversion tables that give slightly nonlinear translations of the "sum-of-subtest-standard" scores.

Results per Taxon

Results for the regression analyses of time and accuracy for each taxon are provided in the subsections that follow.

Visual recognition/discrimination.

Table 23 presents the regression analyses results for the accuracy measure. Note that time measures were not available in the Project A data base for this taxon.

Table 23

Summary of Regression Analyses (with Corrections) for Visual Recognition/Discrimination: Accuracy

ANAME CANAME CAN	1							.	BETA WEIGHTS FOR PREDICTORS	HTS FOR	PREDICTO	RS					
Control Admission 17 22 1 2 <th< th=""><th></th><th>ASVAB COMPOSITE</th><th>MULTIPLE</th><th>ASVAB COMPOSITE</th><th>READING GRADE LEVEL</th><th></th><th>COMPLEX PERCEPTUAL ACCURACY</th><th>OVERALL</th><th>HUMERICAL SPEED & ACCURACY</th><th>PSYCHO- MOTOR</th><th></th><th></th><th>TRAINING</th><th>TRAIMING</th><th>TRAIMING FREQUENCY X RECENCY INTERACTION</th><th>ACCUBACY</th><th></th></th<>		ASVAB COMPOSITE	MULTIPLE	ASVAB COMPOSITE	READING GRADE LEVEL		COMPLEX PERCEPTUAL ACCURACY	OVERALL	HUMERICAL SPEED & ACCURACY	PSYCHO- MOTOR			TRAINING	TRAIMING	TRAIMING FREQUENCY X RECENCY INTERACTION	ACCUBACY	
Consists (CD) .F7 .34 . .11 .29 .	<u> </u>	Herical/Admin		62"	•	•	11.	72	-					•	•	•	
Destrowine Destroy Dest	<u>.</u>	(CO)	73.	.32	•	•	.11	.20		•	•	•	•		•	•	
Total Autiliany (FA) GT - ST -		Bactranics Impair (E.)	73.	.34	•	•	11.	1 .	,	•	•	•	•	,	•	,	
1	55	Field Artiflery (FA)	15.	16.			11.	.20	•	•	•	•	•			•	_
11 12 13 13 13 13 13 13	<u> </u>		97	18:		•	11.	. 10	•	•	•	•	•	•	•		
12 12 13 15 15 15 15 15 15 15	~-	General Technical (OT		82.	•	•	11.	38.	•	•	•	•	•		•	•	_
19		Machenicai Maintenaine MM)	79"	:8:	•	•	21.	.21	•	•	•	•	•		•		
indea67 .3311 (C) 12 (31) .69 .3510		Operators/ Feed (OF)	3.	.92	•	,	.11	92.	•	•	•	•	•	•	•	•	
69 28. 69. (TE) tx		Eurveisi <i>ance/</i> Communica- Communica- Ione (BC)	<i>1</i> 9.	ST.	,	•	#:	61 .	•	•		•	•	•	•		
	لتت	Skilled Technical (ST)		38.	٠		63.	18.	٠	•			•	•	•	•	

Cognitive - numerical.

Table 24 and 25 present the regression analyses results for the accuracy and time measures, respectively.

Table 24

Summary of Regression Analyses (with Corrections) for Cognitive - Numerical Analysis: Accuracy

						BETA W	BETA WEIGHTS FOR PREDICTORS	OR PREDI	CTORS				
ASVAB COSPOSITE	MULTIPLE ASVAB	ASVAB	READING GRADE LEVEL	COMPLEX PERCEPTUAL SPEED	COMPLEX PERCEPTUAL ACCURACY	OVERALL	NUMERICAL SPEED & ACCURACY	PSYCHO-	SIMPLE REACTION SPEED	SIMPLE REACTION ACCURACY	TRAINING	TRAINING	TRAINING FREQUENCY RECENCY
Ĭ.		.52	٠	٠		.31	•			11	.05	0	.02
Combat (CO)	.06	-56		•		.26	٠				.02	11:	.03
Electronics Repair (EL)	-80	95.	•	•	٠	.27	•			•	.05	₩0	.01
Fletd Artiflery (FA)	98"	75.	•		٠	.2%	•				.05	09	.02
General Make- tenance (CD)	• • •	.52	•	•	•	.31	•	•	•		so.	08	10.
General Technical (GT)	90.	-50	•	•	٠	.33	•				20.	60.	.03
Mochanical Maintenance (MM)	.86	24.	•	•	•	.35	,	•		•	.o.	80.	10.
Operators/ Feed (OF)	-89	05.	•	•	•	.32	•	•	•		ş	10	.03
Surveifiance/ Communica- tione (SC)	-86	.56	•	•	•	.28	•	•	,	•	£0.	10	.03
Skilled Technical (ST)	.40	95'	•	•	1	72.	•	·	1	•	90.	•.0₽	.01

Table 25

Summary of Regression Analyses (with Corrections) for Cognitive - Numerical Analysis: Time

						55	BETA WEIGHTS FOR PREDICTORS	HTS FOR	PREDICTO	S.				
ASVAB		MULTIPLE ASYAS	READING GRADE LEVEL	CONTIES PERCEPTUAL SPEED	COMPLEX PERCEPTUAL ACCURACY	OVERALL SPATIAL	RUMENCAL RPEED A ACCURACY	PSYCHO- MOTOR	REACTION SPEED	SIMPLE REACTION ACCURACY	TRAIMING	TRAIMING	TRAINING FREQUENCY X RECENCY INTERACTION	ACCURACY
Clerical/Admi	69°	~10	٠	•	٠	#			. 0	•	-,15	10	80.	29
Cement (CO)	89 . (c	44.		•	,	•		,			-11	13	\$0.	28
Evetimites Bossie (EU)	89.	-113				24	٠		90'-		15	16	90'	30
Field Artifiery (FA)	89. (t	30			,	•	٠	,	\$0	•	-14	15	20.	28
Consers Male Semence (CM)	69. Ci	-:13	-	-	·	\$ 2 ~	•	•	-, 10		-,15	10	8 0°	30
Coneral Technical (GT)	(OT)68	~16	·	•	٠	er-	•		€0"-	•	14	16	•0°	0£*-
Methanical Mulateraners (NEM)		·#·	•	•	•	91"-	٠	·	80 *-	•	14	~18	0 0°	-,20
(Cheraman)	8.	6 k	•	•	•	•	•	٠		•	12	13	90"	20
Surrelllance Cottonings (See (SC)	3 .	-	•	•	٠	~18	٠	•	60	•	-14	-,15	€0*	•2.
Pacheles (ST)		29		,	,	65"-	•	٠	60'-	•	31	16	€0°	28

Cognitive - information processing/problem solving.

Table 26 and 27 present the regression analyses results for the accuracy and time measures, respectively.

Table 26

Summary of Regression Analyses (with Corrections) for Cognitive - Information Processing/Problem Solving: Accuracy

						BETA V	BETA WEIGHTS FOR PREDICTORS	OR PREDI	CTORS				
ASVAB	MULTIPLE ASVAB CORRELATION COMPOSITE	ASVAB	READING GRADE LEVEL	COMPLEX COMPLEX PERCEPTUAL PERCEPTUA SPEED A::CURACY	COMPLEX PERCEPTUAL ACCURACY	OVERALL		PSYCHO.	SIMPLE REACTION SPEED	SIMPLE REACTION ACCURACY	TRAINING	TRAINING	TRAINING FREGUENCY X RECENCY INTERACTION
Clerical/Administrative (Ct.)		.55	٠	•	11.		•	٠	•	•	.03	24	.07
Combet (CO)	.70	.29	•	•	.10	.26	•		•	•	10.	30	.10
Electronics Repair (EL)	.70	55.	•	•	.10	•	•		•	•	.03	24	.07
Field Artiflery (FA)	97.	.34	٠	٠	11.	•	-	•	•	•	00.	26	•0.
General Main- tenance (QM)	70	.31	٠	٠	01.	.25	•	•	٠	•	00.	28	30.
General Technical (GT)	.70	23	•	•	.10	.23	•	•	•	•	.01	27	00.
Mechanical Mainterance (MM)	83 '	12.	٠	•	91.	7 €.	•		•		.01	30	.10
Operators/ Food (OF)	.00	.25	•	·	.10	30	•		•	•	01	.30	.10
Survelllance/ Communica- (fons (3C)	.70	22	•	•	.10	.28	٠	•	•	•	01	29	.10
Skilled Technical (ST)	.70	**:	•	•	.11	•	•	•	•	•	.02	25	20.

Table 27

Summary of Regression Analyses (with Corrections) for Cognitive - Information Processing/Problem Solving: Time

						65	BETA WEIGHTS FOR PREDICTORS	TTS FOR	PREDICTO	RS S				
ASVAB	MULTIPLE ASVAS CORRELATION COMPOSITE	ASVAS	READING GRADE LEVEL	CCMPLEX PERCEPTUAL SPEED	COMPLEX PERCEPTUAL ACCURACY	OVERALL	WUMERICAL SPEED & ACCURACY	PSYCHO.	SIMPLE REACTION SPEED	SIMPLE REACTION ACCURACY	TRAIMING	TRAIMING	TRAINING FREQUENCY X RECENCY)
Cierlest/Admin- istrative (CL)	66.	81.			,	44			1		00	.11	07	£0.
Combet (CO)	.82	.12	•	•	•	69"-	,	,	,		20	01.	07	\$0.
Electronics Frank (EL)	.52	71.	•			47	·	,	ľ		.00	.12	£0	.03
Flaid Arthury (FA)	.52	60'	•	٠	,	97~	٠	·		•	10"-	01.	07	10.
Consers Mile- manners (CM)	.33	81.	•	•	•	.47	•	,		•	.01		07	0.0
General Technical (QT)	88"	91.	•	•	٠	57	•		,		.01	1.	07	60.
Motherical Maintenance (MM)	26.	14.	٠	•	•	-42	•		•	•	02	ę.	07	10.
Operators/ Feed (OF)	.32	83.	٠	•		-,43	÷	,	,		02	01.	07	40.
Burveltance Commentes Sere (SC)	66.	a;		•	•	3	•	•			02	1.	07	á
Skilled Technicul (ST)	28.	.24	•			-,62		•	,		00.	12	* 0	.03

Fine motor - discrete.

Table 28 and 29 present the regression analyses results for the accuracy and time measures, respectively.

Table 28

Summary of Regression Analyses (with Corrections) for Fine Motor - Discrete: Accuracy

						BETA W	BETA WEIGHTS FOR PREDICTORS	OR PREDI	стояѕ				
ASVAS	MULTIPLE ASVAB	ASVAB COMPOSITE	READING GRADE LEVEL	COMPLEX PERCEPTUAL SPEED	COMPLEX PERCEPTUAL ACCURACY	OVERALL	MUNERICAL EPEED & ACCURACY	PSYCHO.	SIMPLE REACTION SPEED	SIMPLE REACTION ACCURACY	TRAINING	TRAINING	FREQUENCY X RECENCY
Clerical/Administrative (CL)	84.	.20	•		•	52				1	.ao	.12	19
Combat (CO)	.76	16.	•	•	,	.42	ė	٠			.28	60.	16
Electronics Ropeir (EL)	.70	.23	•	•	•	**		,			.29	- -	21
Field Ardlery (FA)	27.	.13	•	•	•	47	•				.30	11.	10
General Male- tenames (GM)	.76	.33	•	•	•	143	•	•			.24	60.	16
General Technical (GT)	.75	.16	•	•	•	88.	ı		٠		16.	1.3	20
Mochanisal Maintenanee (MM)	.76	15.	•	•	•	97	•	٠			.28	01.	16
Operators/ Feed (OF)	.74	22.			•	.41	•				.28	.10	•1.
Survellance/ Communica- liece (SC)	.70	.31	•	•	•	.42	ı	•			.28	.10	16
Skilled Technical (ST)	.76	.29	•	,	•	**	•	•		,	.20	.10	17

Summary of Regression Analyses (with Corrections) for Fine Motor - Discrete: Time

	-													
						83	BETA WEIGH	HTS FOR	WEIGHTS FOR PREDICTORS	RS				
ASVAB	MULTIPLE ASYAB CORRELATION COMPOSITE	ASVAB COMPOSITE	READING GRADE LEVEL	COMPLEX PERCEPTUAL 0 PEED	COMPLEX PERCEPTUAL ACCURACY	OVERALL SPATIAL	MUMERICAL SPEED & ACCURACY	PSYCHO- HOTOR	SIMPLE REACTION SPEED	SIMPLE REACTION ACCURACY	TRAIMING FREQUENCY	TRAIMING	TRAINING FREQUENCY X RECENCY INTERACTION	ACCURACY
Clerical/Admin- introdor (CL)	.72	287	•		•	-,53	•	•			.12	£1.	15	•4•
Compat (CO)	.72	28	•	887-	•	3	•	•	•	•	.15	71.	20	99"
Electronics Specie (El.)	57.	~12	٠	07	,	18	,		٠	•	.12	.14	~17	.48
Flats Artificery (FA)	.72	- 64	•	287		-23	•	•	-	•	.12	.13	18	••
Consers Male- tensence (OM)	72	-27	•	88°·	•	•	•	•	•	•	.15	1 :	20	.40
Ganaral Teshnicas (OT)	57.	60"-	•	400		18	٠	·	•	•	.12	.13	-16	48
Machenical Maintenance (MM)	62.	-23	•	98"~	•	•	•	•	•	•	114	11.	10	47
Operators/ Feed (OF)	.72	-27	•	98"	•	•		٠	٠	•	.15	71.	20	48
Survaliance/ Communita- Sons (SC)	.72	-37	•	88"		·	•	٠	•		91.	71.	20	.48
Skilled Technical (ST)	.72	12	·	86"	•	18	-		٠	•	.13	¥.	71	

Gross motor - light.

Table 30 presents the regression analyses results for the accuracy measure. Note that time measures were not available in the Project A data base for this taxon.

Summary of Regression Analyses (with Corrections) for Gross Motor - Light: Accuracy Table 30

	TRAINING FREQUENCY X RECENCY INTERACTION	.05	\$0.	.05	.05	.04	.05	.04	.04	.04	.03
	TRAINING	60	\$0	08	\$0	*0	60'-	\$0. -	08	8 0	07
	TRAINING	05	70 ·	04	50	£0°-	50	70 .	03	7 0'-	.03
	SIMPLE REACTION ACCURACY	•	•	•	•	•	•		•	•	•
ICTORS	SIMPLE REACTION SPEED		•	•	•	•	,			•	
OR PRED	PSYCHO-	.15	61.	.15	14	14	.15	.14	.13	114	.14
BETA WEIGHTS FOR PREDICTORS	NUMERICAL SPEED A ACCURACY	•	•	•	٠	•	•	•	٠	•	·
BETA V	OVERALL *PATIAL	•	•	•	٠	•	•	•	٠	•	
	COMPLEX PERCEPTUAL ACCURACY	•	•	٠	٠		•	•	•	•	•
	COMPLEX PENCEPTUAL \$PEED	•	•	٠	•	•	•	•	•	•	•
	READING GRADE LEVEL		•	·	•	•	•	•	٠	·	•
	ASVAB COMPOSITE	.20	.22	.30	.28	.22	.10	.21	.23	.22	.22
	MULTIPLE ASVAB	18.	26.	18.	.31	.82	18 '	.32	32	24"	26.
	ASVAB COMPOSITE	ClericeVAdmin- istrains (CL)	Combas (CO)	Electronico Ropeir (EL)	Field Artifiery (FA)	General Mein- tenames (GM)	General Technical (GT)	Mechanicai Maintenance (MM)	Operators/ Feed (OF)	Surveillance/ Communica- Hene (SC)	Skilled Technical (ST)

Communication - oral.

Table 31 and 32 present the regression analyses results for the accuracy and time measures, respectively.

Summary of Regression Analyses (with Corrections) for Communication - Oral: Accuracy

	•					BETA V	BETA WEIGHTS FOR PREDICTORS	OR PRED!	CTORS				
ASYAB COMPOSITE	MULTIPLE ASVAB CORRELATION COMPOSITE	ASVAB COMPOSITE	READING GRADE LEVEL	COMPLEX PERCEPTUAL SPEED	COMPLEX PERCEPTUAL ACCURACY	OVERALL SPATIAL	MUMERICAL SPEED & ACCURACY	PSYCHO- MOTOR	SIMPLE REACTION SPEED	SIMPLE REACTION ACCURACY	TRAINING	TRAINING	TRAINING FREQUENCY X RECENCY INTERACTION
Clericel/Administrative (CL)	69"	67'						٠	•		•	•	•
Combai (CO)	09'	92.	•	•	•	.22	•	•	•	•		•	•
Clestrasies O Repair (E);	.40	69"	٠	•	•	•	•	•	•	•	•	•	•
Field . Arithmy (FA)	65"	63"	•	•	•			•	•	•		•	•
General Metri- tenance (GM)	97'	19"	•	٠	·		•	•	•	•	•	•	•
General Teshnical (GT)	65.	.29	•		•	.22	•	•	•	•	•	*	•
Mehrhenical Meintenance (MM)	19.	19"	٠	•	•	•	٠	•	•	•		•	•
Operators Feed (OF)	34'	65.		·	•	·	•	•	•	•	•	•	•
Surveitishee/ Cemmunios- tiene (3C)	·41	14.	•	•	•	•	•	•	•	٠	•	•	•
Shilled Technical (ST)	44	.21	•	•		.20	•	·	•	•	•	•	•

Table 32

Summary of Regression Analyses (with Corrections) for Communication - Oral: Time

						8	BETA WEIGHTS FOR PREDICTORS	HTS FOR	PREDICTO	#S				
ASVAB COMPOSITE	MULTIPLE ASYAB COMMELATION COMPOSITE	ASVAB	READING GRADE LEVEL	COMPLEX COM	COMPLEX PERCEPTUAL ACCURACY	OVERALL	NUMERICAL SPEED 3 ACCURACY	PSYCHO.	SIMPLE REACTION SPEED	SIMPLE REACTION ACCURACY	TRAINING	TRAINING	TRAINING FREQUENCY X RECENCY INTERACTION	ACCURACY
<u>ئ</u>		\$2~		•	٠	•	•	•	11	•			•	ė
Comment (CO)	16.	ez:-	•	•	•	•	•	•	11	•			•	9.
S. Electronica C. Reselt (El.)	18.	.29		•			•		11	•	•	•	•	•.
	18.	65*-	•	٠	•	•	•		10	•	•	•		8 0.
General Made- tenance (GM)	96'	23	•	•	,	٠	•		12	•	٠	•	•	8 0.
General Technical (OT	16'	19	•	•	•	•		•	11	•	•		•	9.
Mechanical Maintenanca (MM)	es.	18"-	•			,	•		12			•	,	8,
Operators/ Ford (OF)	-34	88*-	٠	٠		•		•	12	•	•	•	•	•
Surveillanre/ Communica- deno (3C)	:8:	88 °-		•		•		•	12	٠	•		•	30 °
Skilled Technical (87)	36"	.30	•	•	•	•	•	•	11	·	•	٠	•	€0.

Communication - reading/writing.

Table 33 and 34 present the regression analyses results for the accuracy and time measures, respectively.

Summary of Regression Analyses (with Corrections) for Communication - Reading and Writing: Accuracy

						BETA V	BETA WEIGHTS FOR PREDICTORS	OR PREDI	CTORS				
ASVAB	MULTIPLE ASVAB	ASVAB	READING GRADE LEVEL	COMPLEX PERCEPTUAL SPEED	COMPLEX PERCEPTUAL ACCURACY	OVERALL SPATIAL	MUMERICAL SPEED A ACCURACY	PSYCHO.	SIMPLE REACTION SPEED	SIMPLE REACTION ACCURACY	TRAINING	TRAINING	TRAINING FREQUENCY X RECENCY
-		.46	•	٠	23.	.30	٠		٠		99.	12	50.
Combat (CO)	98"	•0	99"	•	24.	.37	٠	٠	,		\$0.	13	9 0.
Electranica Repair (EL)	18.	*0 *	££"	•	1.2"	.24	•	•	•	•	.07	14	\$0.
Field Artiflery (FA)	187	.17	62"	•	23.	.30	•	•	•		₩0.	13	90.
Ceneral Meln- tenance (GM)	74.	03	\$9"	•	.,92	.35	•	•		•	70.	14	90,
General Technical (GT)	₽9′	.41	•	•	.12	.34	•		•		₹0.	14	90.
Meshenisei Meirrionenso (MM)	\$8'	11	89"	•	-12	.38	•	,			20.	13	90.
Operators/ Feed (OF)	.84	12	09"	٠	21.	.37	•	·	•	•	.07	14	90.
Surveillance/ Communica- Gene (SC)	.89	.20	**	•	21.	.40	•	•	•	•	₩.	13	\$0.
Shilled Technical (ST)	18.	¥0°-	44.	•	.12	.35	•	٠	•	•	.07	14	90.

Table 34

Summary of Regression Analyses (with Corrections) for Communication - Reading and Writing: Time

##1.1916 AEVAS GRADING COMPLEX COMPLEX WIMERCRAL COMPLEX STREET & PSYCHO-COMPLEX STREET & SPEED & PSYCHO-COMPLEX STREET & SPEED & SPEE	CCMPLET WANESCAL PEROL SPEED & ACCURACY SPATAL ACCURACY	SIMPLE REACTION SPEED	SIMPLE REACTION TI ACCURACY FR	TRAIMENG TRAIMING FREQUENCY RESERVEY25 .122612	YRAINING FREQUENCY RECENCY INTERACTION:	ACCUBACY . 13 12
Cleateal/Admin 19 .03				.25 . 12	6 0.	.12
Electromics (CO) .19 .84 .84					0 0.	-12
To the state of th			•	-		ş
## [64] .19 .45		A		-	8 0°	
. 10			•	2512	•00	214
(GT .19 .03			•	2614	.11	17
interat .10 .001010			•	-,25	90.	-,11
			•	2613	01.	*1 ·
		-	,	2411	•0.	12
Communities 19 .05		,	•	2812	01.	~14
Skilled Totalical (ST) 19 .47		•		2512	01.	18

Summary of results.

Table 35 summarizes the results from the regression analyses with the correction factors. Tables 36 and 37 provide comparisons with the regression analyses which were done without the correction factors for time and accuracy, respectively.

Summary of Results (Multiple Correlation) for Regression Analyses with Corrections Table 35

POSITE cel/ injetrative	Discrimination	Visual Recognition/ Discrimination	Numerical Analysis	salysis	Information Processing/ Problem Solving	Processing/ Solving	Fine Motor - Discrete	Discrete	Gross Motor - Light	· Light	Communication - Reading and Writing	ation -	Communication Oral	atton -
cal/ injetrative	ACCURACY	TIME	ACCURACY	TIME	ACCURACY	TIME	ACCURACY	TIME	ACCURACY	TIME	ACCUHACY	TIME	ACCURACY	TIME
(CL)	.57.	A/A	80 .		.70*	.33*	.75*	.72	.31*	N/A	.85*	.19*	.03.	.31*
Combet (CO) .5	.57•	N/A	-98-	.89	-04'	.32•	.76*	.72*	.32*	N/A	.84	.19°	.00	.31
Electronics 6.8	.87*	V /R	*98.	•	.70*	.32*	.76*	.72*	.31.	N/A	.84*	.23*	.40*	.31
Field Artil-	57.	N/E.	•98.	•97	.0 <i>L</i>	.32*	.75*	.72.	.31•	N/A	.84.	.18*	.40	.31•
ein-	.89.	Y/X	39	*	.70*	.33.	.76•	.72.	.32*	A/N	.84*	.20-	.40*	.30*
General Toch-	.57*	M/A	.90	.89	.70-	.33.	.75*	.72*	.31*	N/A	.84*	.18.	.40*	.31
Mechanical Maintenance .1 (MM)	.87•	N/A	.99	3	.89.	.32*	.94.	·c7.	.32•	N/A	*3.	.19*	.41.	.30*
Operators/ Food (OF)	.88.	N/A	.89.	.00	.69	.32*	.94.	.72*	.32*	N/A	.84*	.19•	.40*	.30*
Surveillance/ Communica8 tions (3C)	.87*	N/A	.98-	.89.	.70*	.33*	.94.	.72.	.32*	N/A	# 133 609	.18•	.41.	.31*
Skilled Technical (ST)	.88-	N/A	.98	.00	.70-	.33*	.76*	.72*	.32*	N/A	.84*	.19•	.40*	.32*

Comparison of Results (Multiple Correlations) Without and With Correction Factors: Time

	Visual Recognition Discrimination	ention	Numerical Analysis	netysis	Information Processing/ Problem Solving	Processing/ Solving	Fine Motor - Discrete	Discrete	Gross Motor - Light	r - Light	Communication - Reading and Writing	ation -	Communication Orai	ation -
COMPOSITE	WITHOUT	нци	WITHOUT	WITH	WITHOUT	WITH	WITHOUT	WITH	WITHOUT	WITH	WITHOUT	WITH	WITHOUT	WITH
Cierical/ Administrative (CL)	N/A	K/A	38	•	.23*	.33*	-67	.72.	N/A	N/A	+71.	.19*	.18*	.31*
Cocainer (CC);	M/A	N/A	•	.88	.23*	.32*	.46.	.72*	K/A	W/A	•71.	.18.	.18*	.31*
Electronics Repair (EL)	N/A	N/A	04.	ä	.23	.32*	.67	.72-	N/A	N/A	.21*	.23*	.18*	.31
Flaké Artifi- lacy (FA)	N/A	N;A	9 *.	3	.23*	.32•	.49-	.72.	N/A	N/A	.17	.18.	.19*	.31•
Genera! 'Zain- tenance (GM)	N/A	N/A	86.	3	.24-	.33•	-97'	.72*	N/A	N/A	.18.	.20*	.17.	.30
General Toch- nical (GT)	¥/8	N/A	86.	3	.23•	.33*	-67	.72.	N/A	N/A	. 17.	.19*	.18*	.31•
Meshanical Maintenance (MM)	N/A	N/A	.39	ż	.23*	.32.	.49*	.73*	N/A	A/A	.174	.19*	.15+	.30
Operators/ Fcod (OF)	M/A	N/A	3 5.	3.	.23*	.32•	.49*	.27.	N/A	N/A	•71.	.19*	+21.	.30*
Survolllence/ Communica- tions (SC)	N/A	W/A	.39	.89	.24•	.33*	.48*	-21.	N/A	A/M	.17.	.19•	.17-	.31
Skilled Technics! (ST)	N/A	N/A	Q † .	.83.	.34*	.33*	• 9 }·	.72.	N/A	N/A	+71.	.19*	.19*	.32•
.0.0														

. P . 9.

Comparison of Results (Multiple Correlations) Without and With Correction Factors: Accuracy

	Visual Recognition/ Discrimination	ognittion/ setion	Numerical Analysis	inelysis	Information I Problem	rmation Processing/ Problem Solving	Fine Motor - Discrete	Discrete	Gross Motor - Light	- Light	Communication - Reading and Writing	ation - d Writing	Communication Oral	ation -
COMPOSITE	WITHOUT	WITH	WITHOUT	WITH	WITHOUT	WITH	WITHOUT	WITH	WITHOUT	WITH	WITHOUT	WITH	WITHOUT	WITH
Clerica!/ Administrative (CL)	.31	75.	.39	8.	.46	.70	8 E.	.75	71.	.31	19.	8.	.16	4.
Combat (C3)	.30	25'	24.	98	.43	,70	.38	.76	71.	.32	.60	.84	.23	4.
Electronics Repair (EL)	28.	.57	.40	*	.45	.70	66.	.76	71.	15.	.60	2.	.20	04.
Fletd Arill- lory (FA)	0E"	29.	.40	8.	.45	.70	36 .	.75	.16	.31	9.	18.	.18	9.
General Main- tenance (GM)	88.	89"	8 £.	3 .	.45	.70	.40	.76	÷.	.32	9.	.84	.19	9.
General Tech- nical (GT)	.30	.67	86.	98.	.45	.70	8 6.	.75	71.	16.	09.	19.	.22	9.
Mechanical Maintenance (MM)	.31	49 °	68.	99"	.43	69'	04.	.76	.17	.32	09.	.	.20	₹.
Operators/ Food (OF)	.32	89"	8 E'	99.	.43	69.	.39	.76	.18	.32	09"	.84	.18	₽.
Surveillance/ Communica- tions (SC)	.31	29.	.39	99"	25"	01.	.39	97.	81 .	.32	09.	99.	71.	¥.
Skilled Technical (ST)	.32	.58	.40	.86	.44	01.	36.	.76	.18	.32	09.	78 ′	.23	04.

Description of How the PSFs Will Be Used

Figure 4 provides an overview of how the PSFs will be applied in PER-SEVAL. In the initial steps of a PER-SEVAL application, users provide the input information needed to apply a PSF. To do this, they first assign the duty positions associated with a new weapon system to an MOS. These duty positions were constructed as part of the MAN-SEVAL application. As part of this process a user may identify a new MOS. Once an MOS has been identified, the system will identify an ASVAB composite for that MOS and expected cut-off and mean levels for that composite. The user is then asked to assign each operator and maintainer task to one or more of the MPT² taxons using the taxon definitions provided in Appendix A as a guide. Each task can be assigned to a maximum of three taxons. Users will also estimate the expected percentage of task elements involving each taxon.

In the next step of a PER-SEVAL application, the user describes how frequently the task will be performed on the job. The system then converts this information into estimates of frequency and recency of performance. (The PER-SEVAL design specifications describe this conversion process in detail.) In a later PER-SEVAL step, the system will ask a series of questions that are designed to elicit from users the minimum information needed to estimate the mean level of performance that can be expected given (a) a particular contractor's hardware/software design and (b) the expected quality of the population who will perform the task (i.e., the level of the relevant ASVAB area composite). Page 81 outlines the process that will be employed to obtain these mean values.

Once the taxon assignments have been made and the mean performance values have been obtained, PER-SEVAL begins the process of identifying the minimum level of the ASVAB area composite that will provide the desired performance level—that is the level that will meet the performance requirements identified by SPARC, one of the other MANPRINT aids. There are two components to these performance requirements—a standard which describes the quantitative level of performance that must be achieved and a criterion that describes the percentage of time that level must be achieved. PER-SEVAL identifies the minimum ASVAB area composite by iteratively changing the composite score, calculating the impact of this change on other personnel characteristics, and then using the PSF to estimate expected task performance at the new predictor levels.

The next section provides several examples of how the PSFs will be applied once taxon assignments, mean performance levels, and revised predictor values have been determined. In subsequent

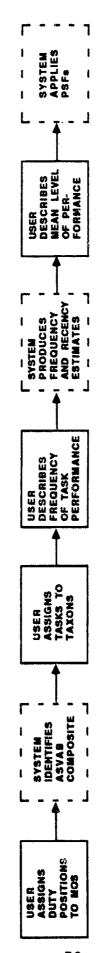


Figure 4. Overview of PSF application.

sections, procedures for estimating the mean performance levels and revised predictor values are outlined.

Example of PSF Application

In this section, we present an example of how the PSFs will be used to predict task performance. The example employs data from the Project A data base. The task used in this example is "Start and Stop a Tank."

The PSFs are applied in a three step process. First, the raw score for the predictor variables are converted to standardized scores. Second, a standardized criterion score is predicted by multiplying each standardized predictor by its beta weight (from the PSFs) and summing the result. Third, the standardized criterion is converted to a raw score. Note that the mean criterion value used in this conversion is supplied by the user. Table 38 displays the results of each of these steps for the example task.

Predictions for task time will be calculated in a similar manner except that task accuracy will be included as a predictor variable. Thus, the accuracy score for a particular task is predicted prior to the time score for that task.

In some cases, a single task may be assigned to several taxons. In these cases, predictions are made for each taxon and a weighted average is calculated, weighing each taxon prediction by the percentage value assigned that taxon by the user.

Assumptions in Applying PSFs

A number of assumptions underlie application of the PSF in the manner described above. The key assumptions are as follows:

- 1) The PSFs we have developed for a taxon can be applied to any task which is placed in that taxon;
- 2) The same predictor-criterion relationships apply over different levels of the predictors and the performance measure;
- 3) Predictor-Criterion relationships do not vary as a function of other personnel characteristics or other variables;
- 4) Users can reliably assign the tasks to taxons and provide the information needed to estimate mean performance levels;

Example PSF Application

TASK (AHH3) PREPARE A REQUISITION

MOS 71L

1. CONVERT RAW PREDICTOR SCORES TO STANDARDIZED PREDICTOR SCORES

	ACCURACY	ASVAB CL	COMPLEX PERCEPTUAL ACCURACY	COMPLEX PERCEPTUAL SPEED	SIMPLE REACTION SPEED	SIMPLE REACTION ACCURACY SPATIAL	SPATIAL	READING GRADE LEVEL	FREQUENCY	RECENCY	FREQUENCY X RECENCY
RAW SCORES (INDIVIDUAL)	•	112	160	-48	-1	108	314	11.3	3.14	2.29	7.18
MEAN (MOS 71L)	60.2	103.8	155.4	-51.9	1.48	102.1	291.3	9.8	2.8	2.6	7.0
8.D. (MOS 71L)	30.1	12.6	19.3	21.9	17.3	14.3	41.4	1.5	•.	æ .	1.7
STANDARD SCORE (INDIVIDUAL)	10.	0.85	.24	.18	14	.41	.55	56 .	.23	38	.12

2. APPLY BETA WEIGHTS

	ASVAB	COMPLEX PERCEPTUAL ACCURACY	COMPLEX COMPLEX PERCEPTUAL ACCURACY SPEED	SIMPLE REACTION SPEED	SIMPLE REACTION ACCURACY	SPATIAL	READING GRADE LEVEL	FREQUENCY RECENCY	RECENCY	FREQUENCY X RECENCY	
BETA WEIGHT (MOS 71L)	.363	.169	.004	.035	016	.248	130	.122	195	65 .075	
BETA X STANDARD SCORE (INDIVIDUAL)	.228	.040	.0007	.005	007	781.	123	.028	920.	600.	.3827

1. ESTIMATE RAW CRITERION SCORE:

WHERE:

X = (PREDICTED STANDARDIZED CRITERION X S.D.) + MEAN 71.7 = (3927 - 30.1) + 60.2

71.7 = PREDICTED CRITERION SCORE

5) The corrections for restrictions of range are based on the following statistical assumptions.

The two sets of prediction equations relating the performance of a task in a given taxon to the scores on the predictor variables were developed using (a) the reference population, and (b) the population of those selected for an MOS. In developing these equations it was assumed that:

$$(i) \quad E(Y \mid X) = E(y \mid x)$$

where Y is the criterion score in the unselected population (a) or (b) and y is the corresponding score for those who have been selected into a MOS. Similarly X is the predictor score in the unselected population (a) or (b) and x is the predictor score for those selected into a MOS.

The second assumption is:

(ii)
$$\sigma_{2Y|X} = \sigma_{2y|X}$$

i.e., the variance of Y partialling out the effect of X in the unselected population is the same as the variance of y partialling out the effect of x in the population selected into a MOS.

These two assumptions are given in terms of a single criterion variable and a single predictor variable. These immediately generalize to the multivariate case and provide the basis for correcting for restriction of range.

Methods for Eliciting Mean Performance Values

In estimating mean task performance within the framework described here, there are three factors that must be considered—the difficulty of the task as determined by the hardware/software design, the overall capabilities of the population performing the task, and the sustainment training opportunities provided to this population (i.e., frequency and recency of task performance). Within the PER-SEVAL framework, we assume that the "overall capabilities of the population" are primarily determined by one type of personnel characteristic—the ASVAB area composite used to control entry into the MOS. We assume that the distribution of the other personnel characteristics (e.g., the new Project A predictors) are determined by the cut-off level selected for the ASVAB area composite. Hence, when identifying a reference population to make the mean judgement, the user has to consider only one personnel characteristic—ASVAB area composite.

Despite this simplification, making a direct judgement of the mean taking into account these three factors is a complex process. The PER-SEVAL program is designed to minimize the complexity of

this process. There are three situations under which the mean values could be obtained (see Figure 5).

First, because PER-SEVAL is designed to be applied later in the acquisition process, it is possible that performance data will be available for the task from test and evaluation. As part of the test and evaluation, data could be collected on mean task time and accuracy, the mean and standard deviation of the ASVAB area composite of the soldiers performing the task, and the training frequency and recency prior to task performance. This information is all that is needed to derive the necessary inputs for the PSFs (see Figure 5).

In the second and third situations, we assume that empirical data on task performance is not available. In the second situation, we assume that the task whose performance we are attempting to predict is measured on the same scale as the Project A tasks (i.e., percent steps correct). In this situation, the system first estimates scores for all personnel characteristics other than ASVAB area composite (scores for the composite were identified in an earlier step). Information on the existing or projected distribution of the other personnel characteristics at various levels of the ASVAB area composite will be available in the PER-SEVAL files. (The projected distributions would be predicted by P-CON.) This information can be used to generate expected mean scores for the non-ASVAB characteristics at a given cut-off level of the ASVAB composite. The user next rates the expected mean level of performance using a behaviorally-anchored rating scale (see Figure 6). The anchors on this scale would depict expected performance levels for Project A tasks falling into that taxon. These levels would be predicted using the PSFs and the predictor values described above as input. It should be noted that this scale should be appropriate for most fine motordiscrete tasks since "% steps correct" is the metric most often used to measure performance on these tasks. Based on previous analyses, we expect 30 to 60 percent of weapon systems tasks fall into the fine motor-discrete taxon. It should also be noted that as PER-SEVAL is applied to a large number of weapon systems, it will be possible to build task difficulty rating scales using metrics other than the Project A "% steps correct" metric. Once the user has input the mean values, he is then asked to enter the expected minimum (5th percentile) and maximum (95th percentile) values for task performance. This information is used to generate a standard deviation for the task.

In the third situation, we assume that the new task is not measured on the same scale as the Project A tasks (i.e., not measured on the % steps correct metric). In these situations, the user follows procedures similar to those described above (see Figure 5). However, rather than using the BARS scales, the user makes direct estimates of mean performance given a mean ASVAB area

composite level and expected frequency of performance on the job. For assistance, a user can ask the system to show what level of performance was achieved on other tasks falling into that taxon given the same levels of ASVAB area composite and frequency of performance. As in the second situation, the user is asked to enter the expected minimum (5th percentile) and maximum (95th percentile) values for the task to provide the information needed to estimate the standard deviation for task performance.

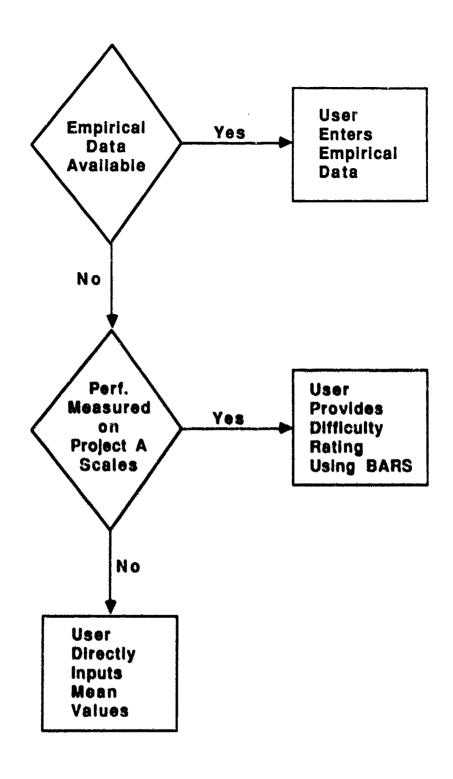


Figure 5. Methods for eliciting mean performance values.

TASK: Start M1A1 Tank Engine MOS: 19E

TASK TYPE: Fine Motor - Discrete EXPECTED SCORE: XXX

ASVAB COMPOSITE: Combat (CO)

EXPECTED FREQUENCY OF PERFORMANCE ON THE JOB: Once a Month

Estimate expected % <u>steps correct</u> for task listed above. Examples of performance levels for other Fine Motor - Discrete tasks are listed below to assist you.

% STEPS CORRECT

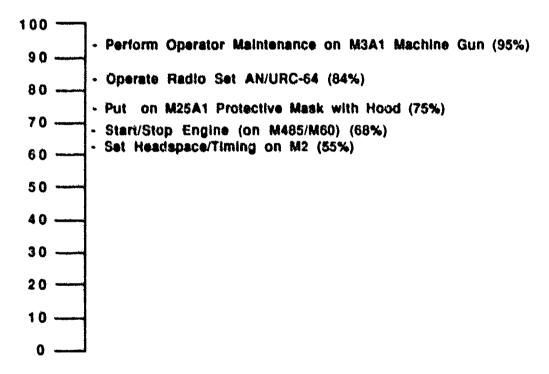


Figure 6. Format for behaviorally anchored rating scale.

Potential Techniques for Validating the PSFs and Associated Concepts

As noted in the introduction, resource limitations prohibited us from validating the PSFs and associated concepts. In this section, we briefly outline key concepts related to PSF application that should be validated and possible validation techniques.

To "validate" the PSF concepts outlined in this paper, there are four key questions that must be answered.

- 1) Can users make reliable taxon assignments?
- 2) Can users make reliable and valid estimates of mean performance?
- 3) Do the PSFs accurately predict task performance? If partially successful, under what circumstances are they successful?
- 4) Is the PER-SEVAL task taxonomy an accurate representation of soldier tasks?
- 5) What is the impact of task performance reliability on the PER-SEVAL estimates?

Question #3 is, of course, the most critical and the ultimate validation question in a psychometric sense. Furthermore, we would argue that if the answer to the first three questions is yes, we would not need to know the answer to the fourth question since the ultimate value of a taxonomy is determined by its utility in predicting performance.

Techniques for Measuring the Reliability of Taxon Assignments

The reliability of the PER-SEVAL taxon assignment plocess can be tested as follows. A group of Army personnel from the same population as the expected PER-SEVAL users can be asked to make taxon assignments for a large number of Army tasks using the portion of PER-SEVAL that assists users in making these judgments. These users would be asked to assign the same set of tasks. Two measures of the "agreement" of task taxon assignment could then be constructed. One measure would assess the percentage of time a task is placed into the same taxon. (The actual measure to be used would be a coefficient of inter-rater reliability.) The other measure would examine the reliability of the taxon percentage assignments. It would be constructed by correlating taxon percentage scores for tasks assigned to the same taxon.

If, as a result of the above analyses, it is found that users are confusing two taxons, improved techniques for describing these taxons should be developed and re-tested. If such techniques are not possible, the taxons should be merged or rearranged.

Techniques for Measuring the Reliability and Validity of the Mean Performance Estimates

Reliability assessment.

The reliability of the PER-SEVAL mean performance estimation process can be tested as follows. A group of Army personnel from the same population as the expected PER-SEVAL users can be asked to make mean performance estimates for a large number of Army tasks using the portion of PER-SEVAL that assists users in making these judgments. Users would be asked to make estimates for the same set of tasks. Correlations between the task estimates could then be examined.

Validity assessment.

The validity of the mean estimates could be assessed by comparing the estimated mean performance estimates with actual values from empirical data. To do this, tasks with existing empirical data would have to be compared with task performance estimates generated by the procedures described above.

Techniques for Validating PSF Performance Prediction Estimates

The PSFs can be used to make performance predictions for a sample of individual soldiers on a number of tasks within a taxon. These predictions can be correlated with actual performance on the tasks. Validation of this type could readily be made using data from the Project A data base. To do this, one would attempt to predict performance on tasks that were not included in the original PSF development effort.

Impact of Task Performance Reliability on PER-SEVAL Estimates

The reliability of hands-on performance tests for individual tasks is relatively low. For example, for the Project A hands-on performance measures, Campell, Campell, Rumsey, and Edwards (1985) report split-half reliabilities for individual tasks that range from .35 to .82 across MOSs. Currently PER-SEVAL produces point estimation of performance for individual tasks that assume perfect reliability. Ideally, if information on the reliability of task performance measures for new systems was available, these point estimates could be converted to interval estimates that would reflect the measures' reliability. Modification of PER-SEVAL to accommodate changes in task performance reliability should be considered in future HARDMAN III improvement programs.

Potential Techniques for Improving the PSFs

In addition to the validation program described on page 87, there are several other studies that could be undertaken to improve the PSFs. As the discussion on page 21 and 47 indicates, at this time we were not able to develop PSFs for several types of tasks. There were several reasons for this. First, the Project A data base lacked data on several different task types related to system performance. In particular, the Project A data base contains one fine motor-continuous task and only a few visual recognition/discrimination tasks. Second, for some task types, particularly those with a small number of tasks, the predictorperformance relationships were weak (see Table 39). Third, for all but a handful of tasks the performance measure used in Project A is "% go"--that is, the number of steps in a task of which the soldier got a "go," divided by the total number of steps in a task. While this measure is directly relevant to fine motordiscrete tasks, it is less relevant to other types of tasks such as fine motor-continuous tasks. For example, performance measures more relevant to fine motor-continuous tasks are "percent hits" (for shooting), root mean square deviation from ideal flight path (for piloting). Measures of this type typically can only be collected in the actual vehicles or in simulators. Because its primary focus was job performance and not weapon system. performance, Project A focused its hands-on assessments to tasks at the soldier's home base.

In future efforts, we recommend that ARI develop more performance shaping functions by collecting additional empirical data from man-in-the-loop simulations at Army simulation facilities. These additional functions would be designed to provide data on the task types not covered adequately in the Project A data base. They could also be designed to provide data on the relationship between performance and key training variables not included in the current PER-SEVAL. For example, PER-SEVAL estimates training as a function of the frequency and recency of performing the task on the job or in sustainment training (these are the training variables most related to training on the job and the only training variables available in the Project A data base). Other key training variables (type and amount of institutional training) are not included in the PER-SEVAL.

We believe that there are a number of simulators which could provide the type of data needed by the PER-SEVAL performance shaping functions. One such simulator is the Realistic Air Defense Engagement System (RADES). RADES is an air defense simulator consisting of subscale aircraft, an aircraft position/location system, actual air defense weapon systems (e.g., Chaparral, Improved Chaparral, Self-Propelled Vulcan, Redeye, Stinger, Roland, and HIVAD), and an electronic interface

Table 39
Current Status of PSF Development

		TIME	ACCURACY	TRAINING FREQUENCY & RECENCY
MPT 2 TA	MPT ² TASK TAXONOMY			
1.1	Visual Recognition/Discrimination	eldslieve ton stud	PSF developed	Included in PSF
2.1	Numerical Analysis	PSF developed	PSF developed	Included in PSF
2.2	Information Processing/Problem Solving	pedojekep 4Sd	PSF developed	Included in PSF
3.1.1	Fine Motor - Discrete	pedojenep 38d	PSF developed	Included in PSF
3.1.2	3.1.2 Fine Motor - Continuous	Not enough tasks in Project A to develop PSF	Not enough tasks in Project A to develop PSF	Not encugh tasks in Project A to develop PSF
3.2.1	Gross Motor - Heavy	Covered in Material Handling Models	Covered in Material Handling Models	Covered in Material Handling Models
3.2.2	3.2.2 Gross Motor - Light	Data not available	PSF developed	Included in PSF
1.4	Communication - Reading and Writing	PSF developed	PSF developed but weak	included in PSF
4.2	Communication - Oral	PSF developed	PSF developed	Data not available - not included in PSF

which connects the weapon to sophisticated data collection and communication systems. Performance measures which RADES can assess include times and ranges for critical engagement events, aircraft identification accuracy, and kill or miss data.

Other simulators which could provide data for PER-SEVAL performance shaping functions include the Crew Station R&D Facility currently under development by the Army Aeroflight Dynamics Directorate and the AMC ARTI program and the developmental SIMNET (SIMNET-D) system at Fort Knox. The September/October 1988 MANPRINT Bulletin described how SIMNET-D could be used to support MANPRINT efforts.

Collection of empirical data from the simulators will be a time consuming process. However, the PER-SEVAL provides a "theoretical" framework which will allow this data to be generalized to a wide range of future systems and tasks -- thus the payoff will be high.

Within recent years, there has been renewed academic interest in examining the factors which moderate or impact the relationship between human abilities and task performance. For example, in recent years there have been several studies on the relationship between human abilities and skill acquisition (see, for example, Ackerman. 1987; Adams, 1987; Henry & Hulin, 1987; Schmidt, Hunter Outerbridge, Goff, 1988 and Ortega, 1989). These studies indicate that the relationship between performance and ability varies as function of type of ability, place in the skill acquisition process, and level of task difficulty. Almost Almost all of these studies used ability measures that are not used by the Army. Thus, it is difficult to generalize their findings to Army personnel. One possible activity under the proposed task order would be to replicate selected academic studies using Army ability measures (e.g., ASVAB, Project A predictors). Results from such studies could lead to more accurate predictions of soldier performance.

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Appendix A

Project A Tasks, Taxons, Weights, and Descriptions

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Appendix A (continued) Project A Tasks, Taxons, Weights, and Descriptions

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Appendix & icontinued) Project & Tasks, Taxons, Weights, and Descriptions

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Appendix A (continued) Project A Teste, Taxons, Meights, and Descriptions

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Appendix A (continued) Project A Tasks, Taxons, Weights, and Descriptions

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Appendix A (continued)
Project A Tasks, Taxons, Weights, and Descriptions

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APPENDIX B. Personnel Characteristics in Project A Data Base

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PROJECT A		ERSONNEL	REASON FOR
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A1AS80AR	New 1980 Stdz ASVAB Subtest - AR	No	Part of Area Composite
A1AS80AS	New 1980 Std2 ASVAB Subtest - AS	No	Part of Area Composite
A1AS80CS	New 1980 Stdz ASVAB Subtest - CS	No	Part of Area Composite
A1AS80EI	New 1980 Stdz ASVAB Subtast - El	No	Part of Area Composite
A1AS80GS	New 1980 Stdz ASVAB Subtest - GS	No	Part of Area Composite
A1AS80MC	New 1980 Stdz ASVAB Subtest - MC	No	Part of Area Composite
A1AS80MK	New 1980 Stdz ASVAB Subtest - MK	No	Part of Area Composite
A1AS80NO	New 1980 Stdz ASVAB Subtest - NO New 1980 Stdz ASVAB Subtest - PC	No	Part of Area Composite
A1AS80PC A1AS80VE	New 1980 Stdz ASVAB Subtest - VE	No	Part of Area Composite
A1AS8GWK	New 1980 Stdz ASVAB Subtast - WK	No No	Part of Area Composite
AIAGOUNA	HAM 1900 GIRT WOAVE GOOTER - MY	NO	Part of Area Composite
A1AC80GL	New 1980 Area Composite - CL <new></new>	Yes	
A1AC8SCO	New 1980 Area Composite - CO	Yes	
A1AC80EL	New 1980 Area Composite - EL	Yes	
A1AC80FA	New 1980 Area Composite - FA	Yes	
ATACROGM	New 1980 Area Composite - GM	Yes	
A1AC80GT	New 1980 Area Composite - GT	Yes	
A1AC80MM	New 1980 Area Composite - MM	Yas	
A1AC80OF	Naw 1980 Area Composite - OF	Yes	
ATACEUSC	New 1980 Area Composite - 80 <new></new>	Yes	
A1AC80ST	New 1960 Area Composite - ST	Yes	
AIAFQTED	New 1980 AFQT Boore	No	Redundant with Area Composite
AIMCATEO	New 1960 Mentel Category	No	Redundant with Area Composite
A1WGT	tifo i o h s	A) a	Analysis of the Africants at the African Advantage
V:AG)	Weight	No	Included in Material Handling Models
A1HGT	Height	No	included in Material Handling Models
AADIABIB	Cintalla Dinad Consum	** -	
AIDIABLD	Disstolic Blood Pressure	No	Included in Material Handling Models
AIPULHEI	PULHES Factor - Physical Stemine	No	fact, at the table
A1PULNE2	PULHES Factor - Upper Extremities	No	Lack of Variability
AIPULHES	PULHES Fector - Lower Extremities	No	Lack of Variability Lack of Variability
AIPULHE4	PULHES Factor - Hearing	No	Lack of Variability
AIPULHES	PULHES Factor - Eyes	No	Lack of Variability
AIPULHES	PULHES Factor - Psychistric	No	Lack of Veriability
A1PULHE7	PULHES Factor - Exp Weightlift	No	Only Available on 1/5 of
			Population
			· -
Accessions C	onatructe:		
ATAQUANT	ASVAB Construct: Quantitative	No	Redundant with Area Composite
ATASPEED	ASVAB Construct: Speed	No	Redundant with Area Composite
ATATECH	ASVAB Construct: Technical	No	Redundant with Area Composite
A1AVERBL	ASVAS Construct: Verbal	No	Recundant with Area Composite
Cognitive Tes	In .		
Contine 188	10 ;		
BIPBAONC	# CORR: Assembling Objects	u	Inc. to Damanaka Managers
BIPSMPNC	& CORR: Map Teet	No No	inc. in Composite Messures inc. in Composite Messures
BIPBMING	# CORR: Maze Teet	No	inc. in Composte Measures Inc. in Composte Measures
BIPSORNC	# CORR: Object Rotation	No	inc. in Composite Messures
BIPSOTNC	# CORR: Orientation Test	No	inc. In Composite Messures
BIPSRENC	# CORR: Responding Test	No	inc. in Composite Messures
			ment of the second of the seco
Cognitive Con	structs:		
8480000	Canalibra Bub Construct. But Autor	A) a	
BIPCORNT	Cognitive Sub-Construct: Spei. Orient.	No	inc. In Composite Messures
83PCREAS 83PC8CAN	Cognitive Sub-Construct: Spatial Ress.	No	Inc. in Composite Messures
BIPCSCAN	Cognitive Sub-Construct: Spetial Scan. Cognitive Construct: Oversil Spatial	No Yes	ino, in Composite Measures
DJF VƏCA I	onfluenta consulaci: nasten phensi	T	•

APPENDIX B. Personnel Characteristics in Project A Data Base (Cont.)

		INCLUDED AS	
PROJECT SOUS		PERSONNEL CHARACTERISTIC	REASON FOR EXCLUSION
Choice Read	tion Time:		
	CRT: Mean of Trimmed Decision Time CRT: Mean Hit Rate	No No	inc. in Composite Measures inc. in Composite Measures
Cannon Sho	ot:		
B3CSCSTS	CS: Mean Abs. Time Discrep	No	inc. in Composite Measures
Number Mem	ory:		
	NUM: Mean for Final Response NUM: Mean Hit Rate	No No	inc. in Composite Measures Inc. in Composite Measures
BOCSNIHIN	NUM: Mean for Initial Input	No	Inc. in Composite Messures
	NUM: Pooled Mean Operation Time	No	Inc. in Composite Messures
Perceptual S	pead & Accuracy:		
	PSA: Mean of Trimmed Decision Time PSA: Mean Hit Rate	No No	inc. In Composite Measures inc. In Composite Measures
Short-Term S	femory:		
	MEM: Mean of Trimmed Decision Time MEM: Mean MH Rate	No No	Inc. in Composite Measures Inc. in Composite Measures
Simple Resor	ilon Time:		
	SHT: Mean of Trimmed Decision Tirre SRT: Mean Hit Rate	Na No	inc. In Composite Measures inc. In Composite Measures
Target Identi	lication Test		
BICSTIDT BICSTINT	TARGET: Mean of Trimmed Decision Tir TARGET: Mean Hit Rate	ne ko No	inc. in Composite Measures inc. in Composite Measures
Target Shoot	:		
B3CSTSDL B3CSTSDT	TARGET SHOOT - Mean Log (Diet + 1) TARGET SHOOT - Mean Time to Fire	No No	inc. in Composite Messures inc. in Composite Messures
Target Tracki	ng 1:		
BICSTIDL	TARGET THACKING 1 - Mean Log (Diat	1) No	Inc. in Composite Messures
Target Tracki	ng 2:		
83CST2DL	TARGET TRACKING 2 - Mean Log (Dist	· 1) No	inc. in Comporite Messures
Total Movem	ent Time:		
BICSRTMT	Pooled Mean Movement Time	Но	inc. in Composite Messures
Predictor Co.	nputer Constructs:		
	Computer Construct: Complex Pero Aco	· A4.	•
	Computer Construct: Num Speed/Acc.	Yes	•
BICCPSYM	Computer Construct: Psychomotor Computer Construct: Simp. React. Acc.	Yes	•
	Computer Construct: Simp. React. Spee		•

Appendix C: Task Taxonomy Taxon Descriptions

I Perceptual

1.1 Visual Pattern Recognition/Discrimination -- Using the eyes to identify or discriminate targets or objects.

Examples: Identify target; identify friend or foe, conduct day and night surveillance.

NOTE: Reading text or numbers is covered under a separate task type (see 4.1-READING/WRITING

II Cognitive

2.1 Numerical -- performing arithmetical or mathematical calculations.

Examples: Measure an azimuth on a map with a protractor, estimate range, determine weight and balance bearing.

2.2 Reasoning/Problem Solving/Decision Making -- encoding or decoding information; classifying objects into categories; troubleshooting or identifying the cause or source of an existing problem or failure; planning or developing a set of procedures for performing future actions; selecting the "best" course of action from a set of multiple alternatives.

Examples: Encode/decode messages. Plan flight. Troubleshoot fuel system malfunction. Troubleshoot electrical system malfunction. Select firing position.

NOTE: A task which involves simple reading comprehension should be categorized under READING/WRITING (4.1). A task which involves reading material and then performing the types of cognitive activities described above (e.g., encoding or decoding) should be categorized under both READING/WRITING and REASONING/PROBLEM SOLVING/DECISION MAKING.

NOTE: Do not assign a task to the REASONING/PROBLEM SOLVING/DECISION MAKING taxon simply because it has heavy memory requirements (e.g., has a lot of steps). Recalling things from memory is part of every taxon.

REASONING/PROBLEM SOLVING/DECISION MAKING should be used when the user is required to perform the types of cognitive activities described above (e.g., encoding or decoding) with the material which is recalled from memory.

III Motor

3.1 Fine Motor

3.1.1 Fine motor discrete. A task involving a set of discrete actions performed in a predetermined sequence. These actions largely involve movement of the hands, arms, or feet and require little physical effort.

Examples: Prepare a DRAGON for firing; Conduct engine shutdown; Assemble SAW; Put On, Wear, Remove M17 Protective Mask; Start and Stop a Tank Engine.

3.1.2 Fine motor - continuous. Continuously performing the actions needed to keep a system on a specified path (e.g., piloting, driving); aiming a gun, weapon or sensor at a target either by pointing the weapon directly or by moving a cursor or other control device; aligning two objects with one another by continuously moving one or more of the objects until they are properly aligned.

Examples: Drive vehicle; Land aircraft; Takeoff aircraft; Aim/sight rifle; Adjust rifle fire.

3.2 Gross Motor

- 3.2.1 Gross motor heavy. Actions involving extensive physical effort or exertion.
 - 3.2.1.1 <u>Carrying/load bearing</u>. Lifting an object, moving it from one point to another, and lowering it. Example: Load ammunition onto howitzer.
 - 3.2.1.2 <u>Lifting/lowering</u>. Lifting and/or lowering an object and unloading or releasing it. Example: Load cannon.
 - 3.2.1.3 <u>Torquing/pulling</u>. Using a wrench or other tool to tighten or loosen a screw, bolt, or other fastener. Example: Adjust tire lugs.
- 3.2.2 Gross motor light. Actions involving movement of the entire body which do not require extensive physical effort.

Examples: Evacuate tank. Get into firing position (for using an M16 rifle). Engage enemy target with hand grenade.

IV Communication

4.1 Reading/Writing -- Reading text or numbers off a hard-copy or CRT; writing with pen or pencil.

Example: Check vehicle record form; Prepare a requisition for publications.

NOTE: Typing tasks involve both READING/WRITING and FINE MOTOR DISCRETE.

NOTE: If the soldier must read a technical manual during performance of task, at least a part of the task should be assigned to the READING/WRITING category.

- 4.2 Oral Communication -- Talking or listening to another person.
- 4.2.1 <u>Face-to-face communication</u>. Talking or listening to another person who is physically present. Example: Issue Order; Use Challenge and Password.
- 4.2.2 <u>Radio/telephone communication</u>. Talking or listening to another person over a radio, intercom, or other electronic medium. Example: Transmit/receive messages; Call for indirect fire.

APPENDIX D

Variance/Covariance Matrices for MOSs Used in Regression Analyses

HOS 11B - Within Cells Variances and Covariances - Time and Accuracy Visual Pattern Recognition/Discrimination Gross Notor Light

	CL	• CO	BL	FA	GN	GT	MM	08	SC	ST	CPAC
CL \$	183.64657										
CO	132.87170	152.44014									
8t	170.98996	137.73115	186.16561								
PA	157.65777	145.15131	152.35839	169.54240							
GM	150.62897	140.44750	176.47294	133.06396	190.43895		•				
GT	170.51478	127.00617	158.50373	138.51952	141.38710	171.76924					
MM	108.10624	129.11246	131.31780	114.48884	146.94217	102.54831	145.10725				
OF	124.92002	131.65197	130.65664	120.08366	142.75817	122.46188	133.63321	141.33653			
8C	153.81561	150.49160	158.40519	139.54911	165.04112	153.44822	138,79647	147.64286	175.26494		
87	173.27334	143.21302	180.66667	154.95133	178.35343	162.29521	134.62626	147.50041	171.26356	201.08683	
CPAC	76.58466	69.92916	71.73774	76.25265	64.29198	73.42623	48.95716	56.10939	70.23145	14.87228	430.35768
CPSP	35.08959	52.33386	19.53659	51.25008	41.47423	30.97022	46.64517	49.84733	41.11725	47.67657	-124,41149
SRSP	16.39540	14.88468	13.86367	21.96179	8.26219	12.39740	11.35229	14.32079	8.73834	15.25938	-7.73550
SRAC	30.32781	31.67426	38.33154	29.83347	39.30234	28.81656	29.97413	28.39350	36.47380	39.89488	55.77347
SPAT	334.90571	333.06918	330.98999	363.89538	301.60713	105.73753	265.39856	280.07109	329.54915	352.50294	294.33094
RCRLVL	20.98313	15.65599	19.48235	17.07585	17.37011	21.12767	12.63639	15.10107	18.89190	19.96377	8.95092
PREQI	1.11201	.59777	.96643	. 22939	1.37178	1.23346	1.02964	1.44699	1.80409	1.80355	-i.04032
RECI	-1.36846	-1.15307	-1.15686	74282	-1.41496	-1.63080	90635	-1.32915	-1.87309	-1.64299	24488
FBB_RBC1	-1.24523	-1.82560	88106	-2.27209	41690	19860	20394	20213	30651	-,19368	-5.15697
TAXONI	2.49230	2.32502	2.14686	2.42543	2.72385	2.29874	2.18008	2.29035	2.57254	2.93353	2.92884
PREQT	-1.82828	-1.89356	-2.24715	-1.66766	-2.41389	-1.96600	-1.82273	-1.76278	-1.93424	-2.06010	13085
RECT	.74589	.69613	.87466	. 49253	1.02452	.82769	.72831	. 79815	.92844	.84689	-1.13418
FRB_RBC7	-2.99194	-3.28063	-3.61261	-3.21743	-3.45177	-3.29573	-2.81475	-2.34561	-2.58579	-2.65832	-5.04515
TAIONT	1.04887	1.12437	1.04066	1.05229	1.26678	. 30544	.96682	1.18644	1.17996	1.37070	.79759
	CPSP	3R3P	SRAC	SPAT	RORLYL	PREGI	2501	FRE_RECT	TAIONI	FREQT	RECT
ARED.											
CPSP	482.70804 124.20694	110 11104									
583P	14.05406	330.37709 21.46721	247.65530								
8RAC Spat	308.71227	124.29382		2083.16460		•					
RORLVL	3.74854	1.56408	3.64390	37.49829	2.61523						
PREQI	1.11641	1.77241	21090	3.08012	. 14881	2.09572					
RECI	.23445	39157	55648	-2.51305	19317	-1.25219	1.82753				
MBUI	.63149	-193191	- 133646	-6.31303	13911	-1.63613	1.08194				
	CPSP	3 2 3P	SRAC	SPAT	BCBLVL	FREGI	RECI	PRE_REC1	TATONI	FREQT	EEC?
FRE RECI	3.42615	4.23829	-1.95178	-3.33315	10489	2.26354	.56153	10.32017			
TATONI	1.23424	.17420	.82142	8.54585	. 28589	01458	.01655	02082	.55945		
FREQT	1.12444	.32679	58189	57591	24104	.56644	23368	1.03573	06849	1.24240	
RECT	18405	. 28569	00304	-2.81369	.09897	12279	.20023	.29723	.03958	49497	1.02763
FRE RECT	1.21664	1.03963	-2.01292	-1.44697	41024	1.31727	.04065	4.17131	05110	2.31474	1.11539
TATONT	1.88843	1.69218	.56168	3.88866	. 19462	.10850	09128	.07402	.07571	.01180	03221
	FRE RECT	TAIONT									
	~			•							
PRE_RECT	10.61836					٠.					
TATONT	03257	.60037				•					

MOS 198 - Within Cells Variances and Covariances - Time and Accuracy
Fine Motor Discrete
Communication - Oral

	CL	t 03	BL	PA	GM	· GT	HH	0.	8C	ST	CPAC
CL \$											
CO	138.12533	163.90781	*** ****								
BL	185.72525	151.48362	208.74674								
FA	163.92285	152.35572	166.01184	176.22790	414 54444						
GN	163.74452	156.63886	197.85759	145.86485		185 1886					
GT	179.37215 113.27263	134.98149 145.24309	174.86234 145.24817	146.20598 123.14156	157.62112 165.72181	182.19028 112.06255	166 94981				
MM OF	124.28592	140.35751	139.12080	123.08232		125.52255	166.24751 148.68601	144 40610			
9C	160.31205	161.05621	172.81890	147.17799	180.91941	163.31235	152.39827	148.80610 154.76549	185.40348		
3T	182.50054	150.58647	197.30414	163.23948	193.81202	173.67443	143.95692	151.79104	180.59467	214.71018	
CPAC	91.07387	81.41279	97.72603	91.29061		80.83585	69.86383	69.21244	18.04899		536.36600
CP8P	28.43136	25.68347	33.28439	34.41786	22.49085	29.36857	21.02697	22.96880	23.31559		-183.94161
PSYM	161.70246	180.41296	169.76029	180.27638	151.31088	154.79903	135.91967	141.05161	156.27543	184.00897	257.32380
3RSP	21.95327	17.85138	20.89670	27.48397	9.25714	21.42764	10.52325	14.68464	14.35480	24.55024	29.88519
SBAC	24.45210	33.23197	30.22650	24.01938	37,42200	27.52195	36.50138	35.22171	39.72431	35.20242	57.03834
SPAT	356.88335	340.98613	384.49189	373.75167	353.71562	330.46458	299.25243	290.65283	351.84199	382.54126	329.56076
FR804	-1.66614	-1.79765	-1.57190	-1.71399	-1.54102	-1.69541	-1.49190	-1.59493	-1.80865	-1.65090	-2.81268
REC4	1.42591	1.21260	1.65437	1.30831	1.60876	1.33003	1.17981	.9993(1.40202	1.53023	1.59522
FRB_REC4	.22436	-1.07713	.86169	60104	.56733	02217	76388	-1.35965	36417	.03699	-3.08441
TAZON4	.53074	. 66248	. 82785	.63706	.95220	.37929	.75311	.58067	.70542	.19568	.61214
TIME4	-1.00901	-1.49482	-1.52519	-1.19891	-1.74482	-1.09351	-1.67231	-1.43797	-1.46555	-1.38950	.08325
TAIONSA	1.27326	1.38079	1.49269	1.24508	1.58195	1.25546	1.43214	1.21791	1.55940	1.34254	.07655
TIMBBA	-1.31833	-1.14046	-1.28439	-1.42664	98631	-1.26589	62922	89489	-1.06069	-1.54073	21140
	CPSP	PSYN	3257	SRAC	SPAT	PB894	REC	FRE_RECO	PHOLAT	TINB4	A8HOLAT
CPSP	484.84197										
PSYN		1216.24908									
383P	90.20388	150.40499	219.63431								
SRAC	7.40852	79.80849	34.32156	163.39568							
SPAT	216.94415	106.78131	107.52000		1760.93164						
FR194	1.20309	-1.06571	. 96605	21994	-4.84254	.82718					
REC4	.19454	1.79875	25110	.91503	4.58025	40117	. 55072				
FRE_REC4	3.10321	01012	.59245	1.99981	2.10256	.65017	.60663	3.91444			

	CPSP	PSTN	588P	SRAC	SPAT	PEROL	EEC4	PRE_REC4	PAZONE	TIMEA	ASHOLAY
TAION4	. 23325	1.00687	.02201	.62029	3.17418	.01734	06682	.06162	.17452		
TEMBA	-1.92213	-2.63254	25660	06552	-5.73067	08979	.05460	08824	08298	. 30767	
TAXONSA	.10384	1.90857	,27809	.01562	4.16509	.07155	04623	02999	.01910	06241	.37554
ASEMIT.	-1.07633	-3.26339	-1.49898	.01138	-2.80082	01261	.04100	.01925	.04306	.07289	.02159
	TIMESA										
TINESA	.61743										

HOS 31C - Within Cells Variances and Covariances - Time and Accuracy Cognitive - Beasoning/Problem Solving/Decision Making

	CL	t CO	BL	FA	GM	GT	MM	OF	\$ C	31	CPAC
CL ‡	165.25004										
CO	98.50251	124.87847									
BL	150.31461	113.67266	168.28208								
PA	134.15899	113.69662	130.83617	143.54885							
GM	120.80093	117.11880	154.86321	106.31857	169.84553						
G T	148.30433	92.17901	135.74630	112.13327	109.69337	148.38786					
HH	75.79810	109.13442	109.52056	85.50878	130.12588	71.87200	131.52660				
OF	88.52535	97.01713	100.90309	84.57235	111.63647	86.32414	105.63585	101.21787			
9 C	128.54511	129.21592	142.35548	116.14400	147.95145	127.95096	126.52615	120.95472	163.39163		
ST	150.57336	112.31395	160.22946	130.72581	150.28336	137.32109	108.94963	113.56417	150.27280	178.23539	
CPAC	36,33004	25.52761	39.87018	31.90690	36.83382	32.66248	17.92150	20.92645	26.22090	39.74705	468.41568
CPSP	40.71973	40.80756	48.18224	50.77840	40.60048	32.13131	36.76548	29.91995	36.84112	44.85855	-227.40172
ARMM	167.76344	105.44590	149.33187	151.93343	102.33841	147.60294	63.84921	77.02688	106.88817	129.03567	40.16929
SRAC	29.70639	26.30044	34.06546	31.96610	27.05801	28.51723	22.01523	19.19210	27.22665	32.86518	22.77149
325P	19.66290	14.22803	24.87902	20.73443	19.75718	16.44072	15.23325	10.82293	13.69236	19.23319	-15.03969
TAGE	297.58010	285.77720	306.03657	324.31589	274.66613	258.21293	219.82199	221.25190	303.35449	330.58388	190.51488
BOBLAL	18.40773	11.53512	16.88140	13.91850	13.69919	18.44618	8.98088	10.75656	15.96816	17.03864	3.96040
pregj	25928	1.03643	.28742	.37654	.65151	08578	1.44920	.78001	.90399	.01405	1.83842
reci	-1.22104	-1.35206	-1.44277	-1.31702	-1.35462	-1.19274	-1.35442	-1.09732	-1.46848	-1.22273	02308
PRB_REC3	-4.38080	-2.28201	-3.63675	-1.42032	-2.11360	-4.01947	-1.20377	-1.98619	-2.81671	-3.56252	4.72848
TAIONS	2.13591	1.55551	2.22778	1.98330	1.90577	1.81270	1.25867	1.23137	1.68014	2.05968	2.05839
TINES	60601	87110	69485	99758	52396	54481	69277	64163	61509	55280	16899
	CPSP	ASKE	SRAC	3837	SPAT	BORLAL	FREQ3	BECS	188_88C3	TAIOBS	TINES
CPSP	495.18861										
ABHK	150.02122	568.20944									
SRAC	6.94361	34.40341	214.14505								
323P	103.37751	10.72928	-6.20842	180.65233							
SPAT	227.16520	372.45683	53.08736	93.44333	1685.18131						
RCRLVL	4.17871	18.56694	3.61461	2.22238	32.13157	2.31009					
FREQ3	-1.90137	. 11960	-1.05850	-1.50970	-2.61961	01646	1.21039				
REC3	-1.01212	-1.18152	1.30522	.43124	-1.22671	14349	11111	13118.			
PRE_RECJ	-6.97011	-3.95254	2.22513	-2.21591	-12.31933	41213	. 82885	.97289	6.31427		
	CPSP	MASA	SEAC	383P	SPAT	BORLVL	FEE Q3	8 8C)	188 _88C)	TAION3	11883
TAIONS	07354	2.53344	.66394	.13222	5.59749	. 22116	.16028	14819	06 23	. 28211	
Tines	97909	-2.46653	.27302	48469	-4,92641	01616	05519	.04224	01386	01661	. 15238

HOS 71L - Within Cells Variances and Covariances - Time and Accuracy

Communication - Reading/Writing

	CL	* CO	BL	PA	CM	GT	HH	OF	S C	31	CPAC
CL ‡	159.27906										
CO	115.62215	155.30721									
BL	153.90041	129.48767	177.10645								
FA	134.85247	138.14987	138.22666	151.76153							
GM	139.00220	139.45175	173.75370	127.44935	192.56149						
GT	144.98569	108.84841	137.28461	116.05994	123.91493	145.85151					
MM	87.97482	125.67440	118.26228	103.66913	140.72438	18.84803	135.21418				
0F	99.20744	120.37037	111.45135	102.16574	128.99000	95.33217	116.95355	118.76063			
3C	135.77781	149.70663	147.79963	132.18578	159.30749	132.96984	130.92140	132.92192	168.11118		
3 T	151.18904	132.20615	165.06362	137.82444	161.41659	137.92150	118.81347	125.91031	156.25815	178.73498	
CPAC	60.78063	60.59089	83.55875	64.10531	60.64750	55.50674	44.39350	47.48837	81.00228	66.25508	361.17274
CP8 P	27.47515	48.52187	12.57489	43.77097	48.94401	20.78127	43.72172	37.11939	41.14477		-131.08711
SRAC	29.19494	26.23658	28.14310	23.91362	29.03917	33.02707	19.19328	26.58608	30.75571	34.75682	57.04816
SRSP	.11347	15.71048	. 43983	11.23040	00548	3.06924	2.64166	3.94643	5.68439	. 26005	-3.73404
SPAT	306.33986	329.21234	328.61228	338.23569	320.66022	273.16338	262.77733	261.07986	337.53364	345.75324	256.76220
RGRLVL	17.97934	13.54736	17.07269	14.44980	15.37635	18.06821	9.77372	11.78844	16.48952	17.39931	6.86623
4556 \$.01625	.11028	16617	.45650	43651	14920	34856	32400	39918	24974	55479
RECS	34368	06935	12274	42825	. 12579	16635	.24931	.05764	.10176	16761	11642
FRE_RECE	-2.10908	-1.36451	-2.07832	81670	-2.34272	-2.50413	-1.33154	-1.90627	-2.41688	-2.26811	.64240
BHOLAT	2.55023	2.00021	2.33733	2.41725	2.00924	2,19291	1.24593	1.48469	1.98626	2.33052	2.11662
TENBS	25878	25235	. 25626	21080	.35624	40725	.23174	19989	10545	.03969	82054
	CPSP	SRAC	8857	SPAT	RCBLVL	FREQE	1461	PEL_ELCI	SHOLAT	TINES	
CPSP	479.02324									•	
SRAC	-31.54784	199.34840									
SESP	71.18250	1.21583	182.06507								
SPAT	219.48050	69.00951	53.43266	1871.01617							
BORLAL	2.61066	3.96018	. 35804	33.85572	2.25531						
FREQU	.94654	. 15709	. 16469	1.94937	01399	.83188					
etci	41635	10013	.01011	-2.61995	02381	68679	.46374				
FRE_RECE	.10595	01401	.46428	-4.22552	30060	.40401	.11095	2.54261			
TAXONS	.64212	.10189	. 40164	1.44403	.27884	.14811	12510	.06367	.23416		
TIMES	-1.20449	58158	. 22175	-1.61988	04787	10109	.01590	04126	04449	.56118	

MOS 95B - Within Cells Variances and Covariances - Time and Accuracy
Cognitive - Numerical
Fine Motor Discrete

	CL	t CO	BL	PA	GN	GT	HH	90	SC	51	CPAC
ՇՆ ‡	88.94946										
CO	57.30364	94.98460									
BL	73.72800	60.65891	84.26511								
FA	80.33972	81.88018	71.21450	99.84914							
GN	52.56569	65.01889	74.21795	53.25113	88.15212						
GT	77.24647	54.71439	64.24970	65.92630	45.89536	78.51556					
KN	37.14640	77.91480	57.26024	55.16474	75.46014	36.05555	93.33444				
OF	42.61789	69.98678	46.65345	53.65263	59.36730	43.04882	14.25017	10.78325			
3C	57.66193	78.28907	60.69639	63.09997	67.77399	59.55668	71.99173	67.23663	81.49151		
9 7	61.51069	53.44665	64.01344	60.31494	61.07758	54.59528	49.11607	19.91046	58.86446	66.17313	
CPAC	21.07260	20.29309	14.87112	26.81029	8.43748	17.87225	9.75407	11.19100	10.28241	9.14178	416.10412
CPSP	16.32702	22.83994	13.30131	29.09428	11.83312	9.20014	19.39475	21.51076	15.61036	20.20414	-171.15935
ABMK	100.50395	72.67536	77.08681	102.85196	45.61892	86.36134	52.01336	81.79405	52.13401	54.05943	27.14755
PSTM	40.45112	74.33015	47.89860	71.29028	14.21348	34.58194	74.30286	61.37648	56.25361	39.90167	121.17299
SRAC	11.94574	13.35588	12.41189	14.88022	11.17939	10.49325	13.86796	13.29315	10.17381	11.14889	35.99515
3 R 3P	10.41498	13.25145	7.33021	16.93802	3.49439	9.82206	1.56814	11.34845	6.78895	9.03572	-1.16334
SPAT	137.30931	174.01083	139.09558	183.14817	122.02137	118.31398	141.38111	126.70119	150.91191	128.82223	132.76218
PREGZ	.07753	.58127	.40727	. 46694	. 49661	14313	. 43777	. 19586	.32063	. 22226	21427
BECS	51083	10561	60422	58579	42506	42465	20515	17024	41006	56049	. 26906
and becs	-1.21756	. 20654	32441	25841	. 19625	-1.77150	.55628	20116	54751	18751	00437
TATOMS	1.41187	1.68387	1.54405	1.74302	1.43911	1.19642	1.42005	1.21392	1.49253	1.33159	.59495
11422	81334	-1.40198	73230	-1.42192	66817	10861	-1.08808	-1.13385	-1.01454	83360	75802
1510(28729	.34571	.01221	.04317	. 23040	17940	.16986	05105	. 09235	11331	50182
8804	49142	27675	19148	42365	33344	12254	05379	14165	24177	33381	.52819
PRE BECI	-2.55526	56104	-1.42366	-1.53019	87485	-2.31164	11683	59861	-1.04610	-1.61879	.\$3532
PARONA	.54154	1.04129	.0547	,87185	1.01252	.14802	1.06159	.1444	. 10154	.73445	.17198
Tine4	22513	71944	49713	42917	11233	22334	84581	61811	69342	48810	. 12418
	CPSP	RHSA	PSTH	SEAC	3237	SPAT	FREGR	EECL	FEE_LICE	TATORE	TIREL
CPSP	453.02147										
AENN	164.08016	524.5594)									
PSTM	156.95464	197.85183	1133.93637								
SEAC	4.74253	15.36782	24.24955	131.22030							

Within Cells Variances and Covariances MOS 95B (CONT.)

	CPSP	* NESA	PSTN	SRAC	SRSP	SPAT	PREQ2	RBC2	FRE_REC2	SMOZAT	TIMBS
SESP :	79.17609	47.39801	81.79522	-3.91821	101.47392						
SPAT	212.58395	229.73998	447.24701	52.14851	59.73899	1240.70005					
PREQ2	1.27908	00665	3.81184	.31709	.59375	2.25146	.87337				
REC2	-1.33168	-1.13159	-3.41655	18211	24633	-1.50435	46005	.71202			
FRB_RECZ	.52986	-3.56713	3.10309	.61902	1.27679	3.44668	1.20279	.52187	5.13212		
TATONS	. 93939	1.64467	2.23740	.31480	.15515	5.80840	.10799	09555	.06061	.31339	
TINE2	-1.44838	-1.53824	-3.08520	13893	84241	-4.50485	-:04165	00012	09923	08836	.40979
FREQ4	.82464	37212	2.71254	.20281	.48516	.55885	.61575	27948	1.04883	.06102	02254
REC4	97183	98010	-1.49374	09528	20199	76565	27086	.39541	.20641	05362	.00261
FEB REC4	92876	-3.82665	2.59227	.34626	17633.	00714	.52550	.59667	3.23525	91770	05133
TAION4	1.51348	1.56869	2.45891	.25160	.30001	4.73619	.11669	07929	.12739	.10385	05415
TINB4	-1.40357	-1.04296	-2.15584	-10984	41800	-3.27371	06650	.03411	09564	06132	.04664
	72201	RECI	PRE_REC4	PHOIAT	TIME4						
FRIQI	.71151										
REC4	28112	.45599									
FRE_REC4	.73062		4.32246								
PHOZAT	. 10029	06479	.01711	.23019							
TIMB4	01978	.02100	03728	04917	.15497						

* Variables in rows and columns use the following motation:

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Variable Label
  SPAT
             Overall Spatial
  RORLYL
              Reading Grade Level
  CPAC
              Complex Perceptual Accuracy
  CPSP
             Complex Perceptual Speed
  NASA
             Numerical Speed & Accuracy
  PSTA
             Paychomotor
  SRAC
             Simple Reaction Accuracy
  323P
             Simple Reaction Speed
  CL
             ASVAB Composite - CL
  CO
             ASVAB Composite - CO
  BL.
             ASVAB Composite - $L
  FA
             ASVAB Composite - FA
  CM
             ASVAB Composite - GM
  GŤ
             ASVAB Composite - GT
  M
             ANYAB Composite - MR
 07
            ASVAS Composite - 07
 30
            ASVAB Composite - SC
 37
            ASVAB Composite - 37
 PREGI
            Training Prequency - Vigeal
 RECI
            fraining Lecency - Figual
            Training Prequency-Secrety Interaction - Visual
 FER RECT
 TATONI
            Accuracy - Viewal
 FEE01
            Training Frequency - Maneric
 SICE
            Training Recency - Buneric
 FRE EECZ
            Training frequency-Receasy Interaction - Heneric
 TIMES
            Time - Memeric
 TATORE
            Accuracy - Evmeric
 FEROI
            fraining frequency - Cagnitice
 tect
            Training Recency - Cognitive
           Training Prequency-Receasey Interaction - Cognitive
 FEE ERCL
TIRE?
            Time - Cegitire
 TATCHE
           Accessor . Cognitive
11501
           Training Frequency . F.M. Discrete
HCI
           Training Recessy - F.M. Discrete
m uci
           Training frequency-lectency Interaction - P.M. Discrete
tinti
           fine - f.E. Dircrete
TATORE
           Accuracy - F.W. Discrete
fetof
           Training frequency - G.B. Light
HCI
           fraining Recency - Q.M. Light
fet etcf
           fraining frequency-lecency Interaction - G.E. Light
TATORY
           Accesses - G.M. Light
feres
           Training Frequency - Com. E/F
EECS
           Training Recency - Comm. 2/V
mi elci
           Training Prequency-Recescy Interaction - Com. E/F
TIRRE
           Time - Coop. E/V
TATORS
           Accuracy - Com. E/V
TIBREA
          five - Come. Oral
TATOKAL
          Accersoy - Come. Oral
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